



# Electrical Machine Design – I (170902)

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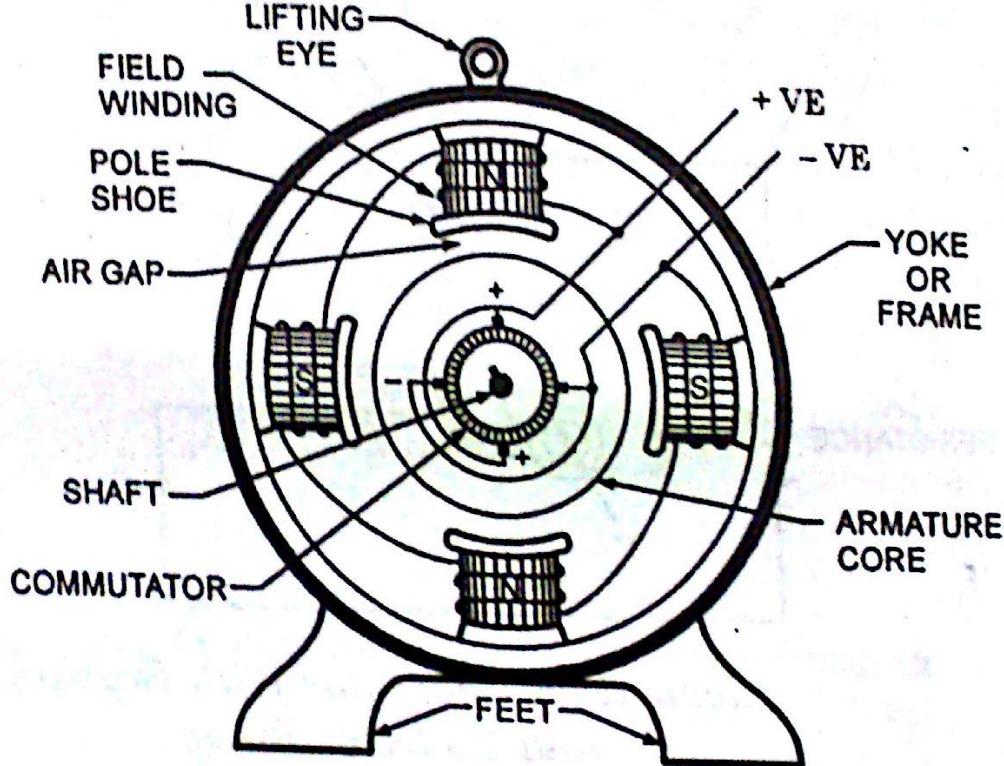
# DC Machine Construction

- **Field System**
  - **Yoke/ Frame**
  - **Pole Core**
  - **Pole Shoes**
  - **Magnetizing Coils**
- **Armature**
- **Commutator**
- **Brushes**
- **Bearings**
- **Shaft**

# DC Machine Construction

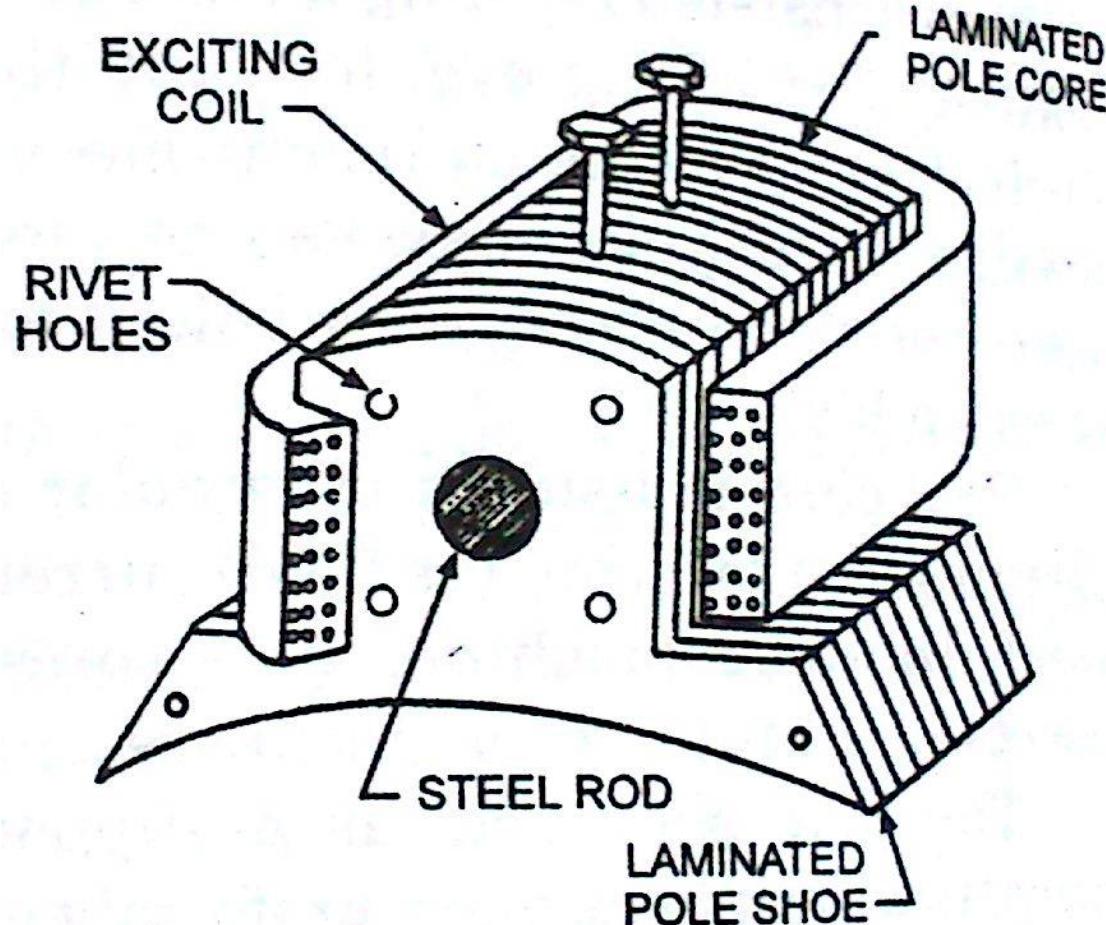
- **Armature**
- **Commutator**
- **Brushes**
- **Bearings**
- **Shaft**

# Yoke / Frame



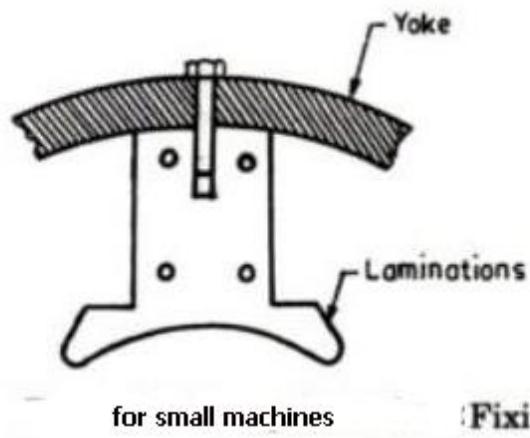
4-Pole DC Machine

# Pole Core, Pole Shoes, Magnetizing Coils

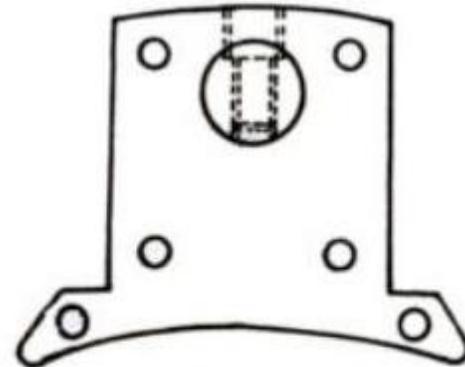


*Laminated Pole Core and Pole Shoe*

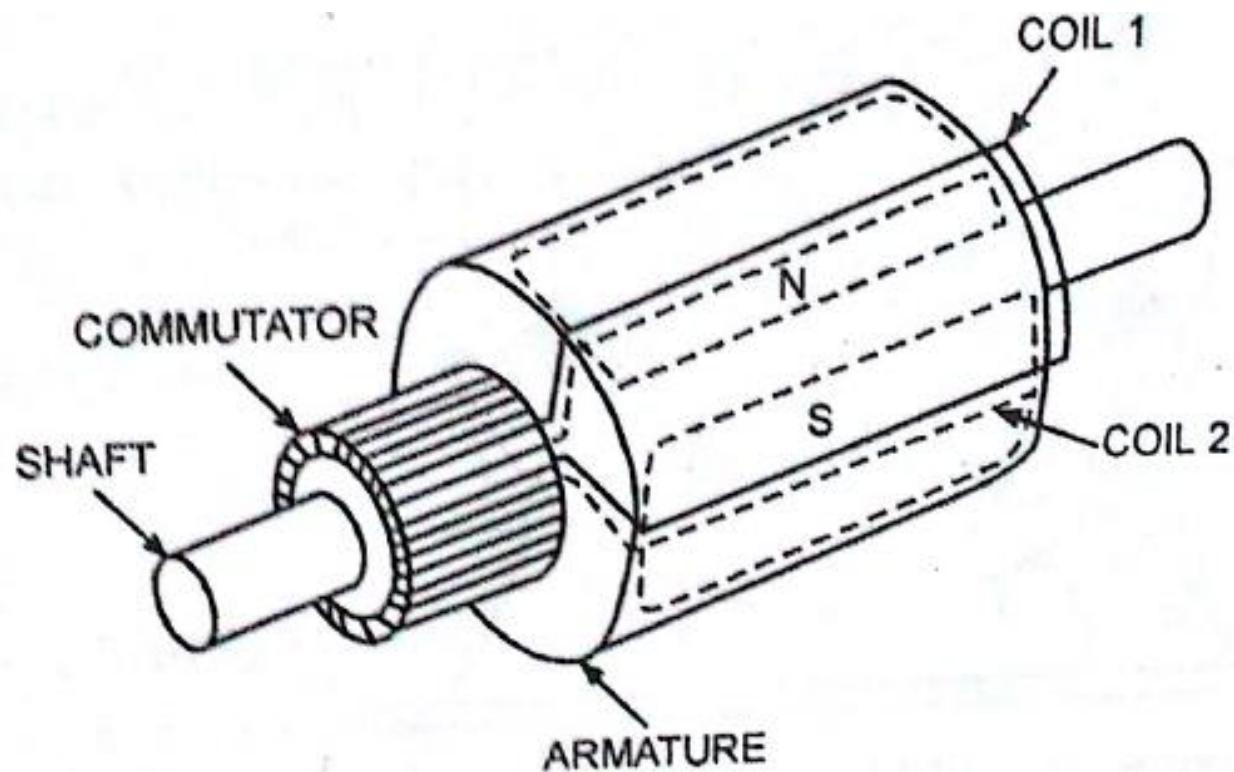
# Pole Core, Pole Shoes, Magnetizing Coils



Fixing pole to the yoke.



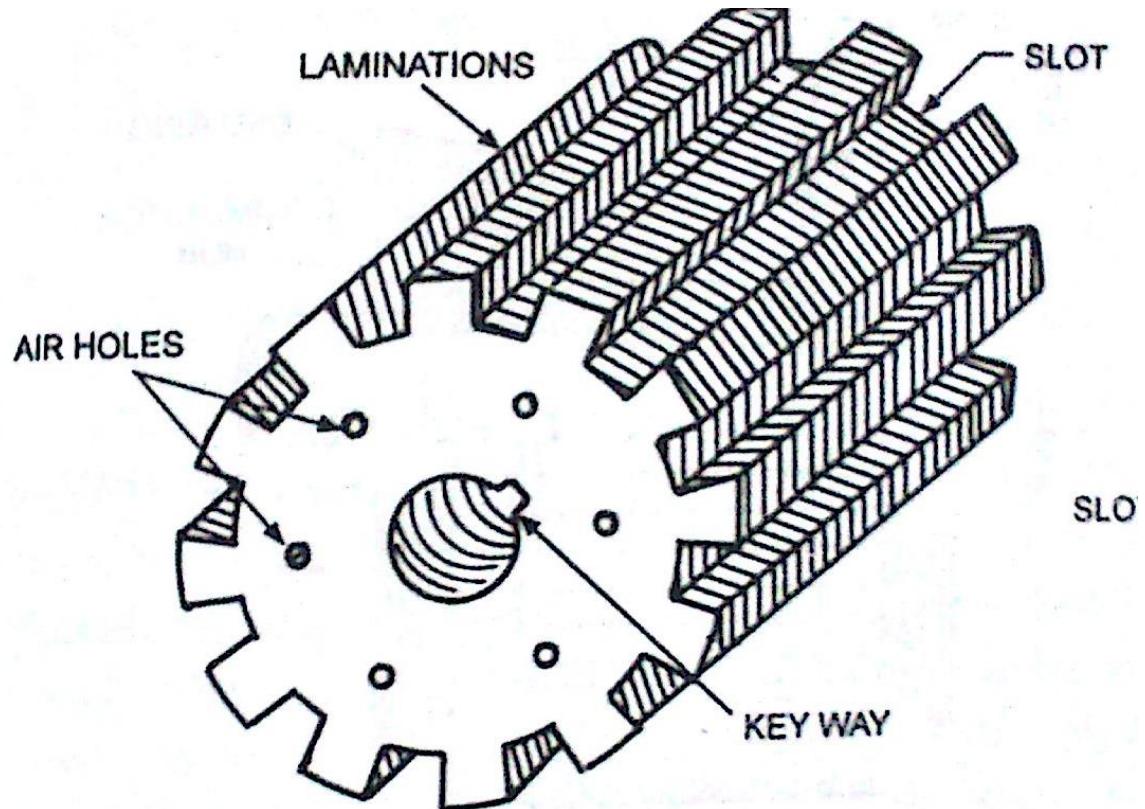
# Armature



(a) *Longitudinal View of Armature*

*Armature*

# Armature Lamination

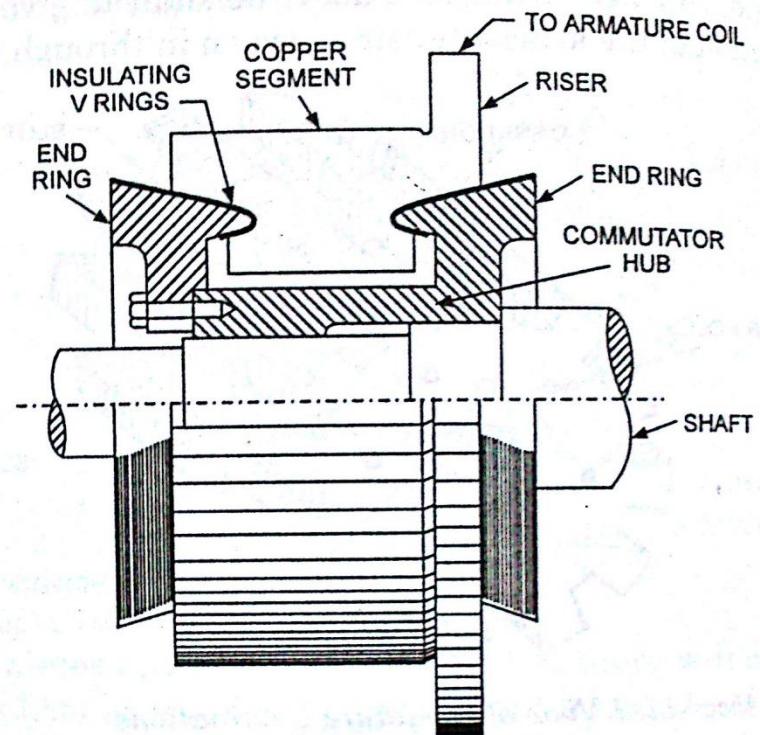
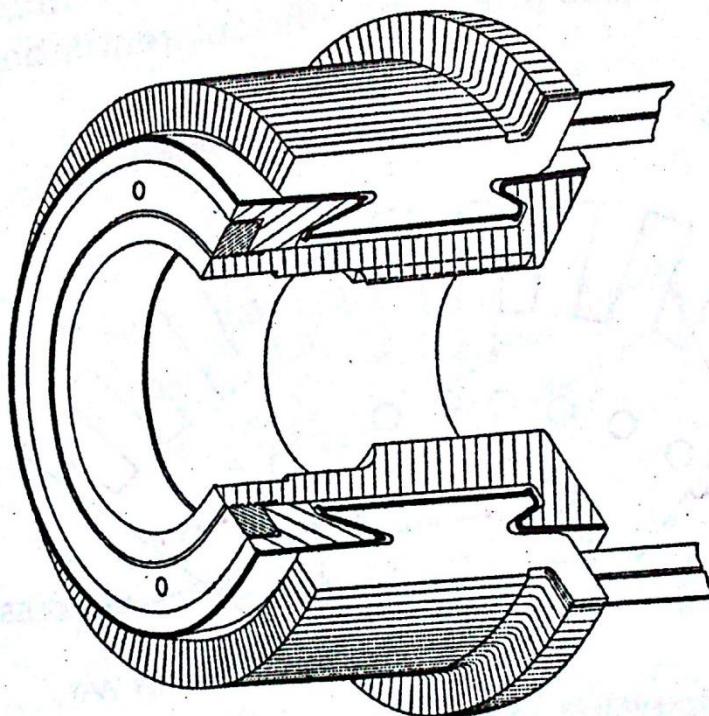


*Assembled View of Armature Laminations*

# Armature

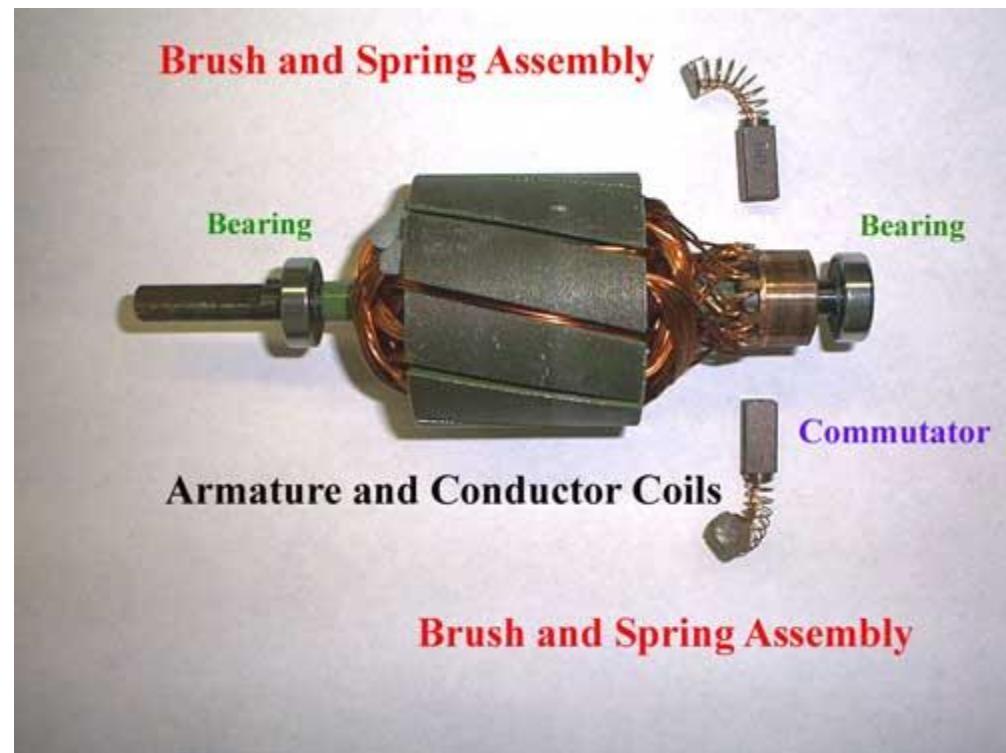
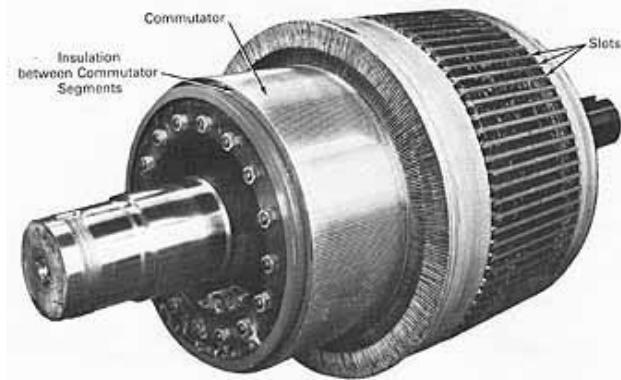


# Commutator

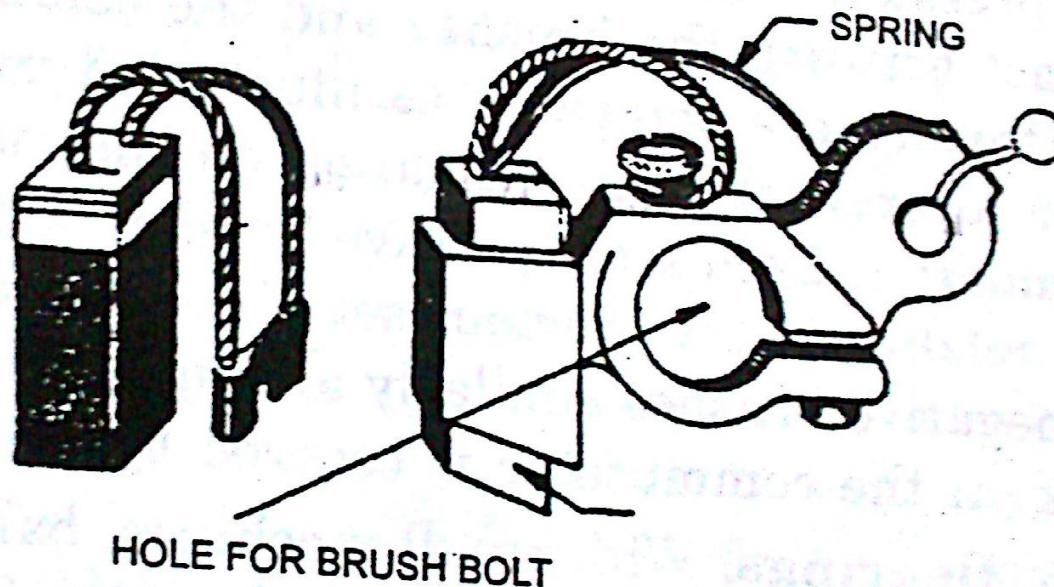
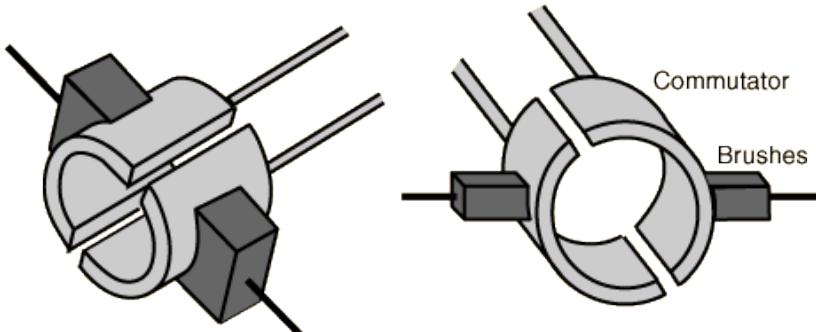


(b) Section View of Commutator Segments

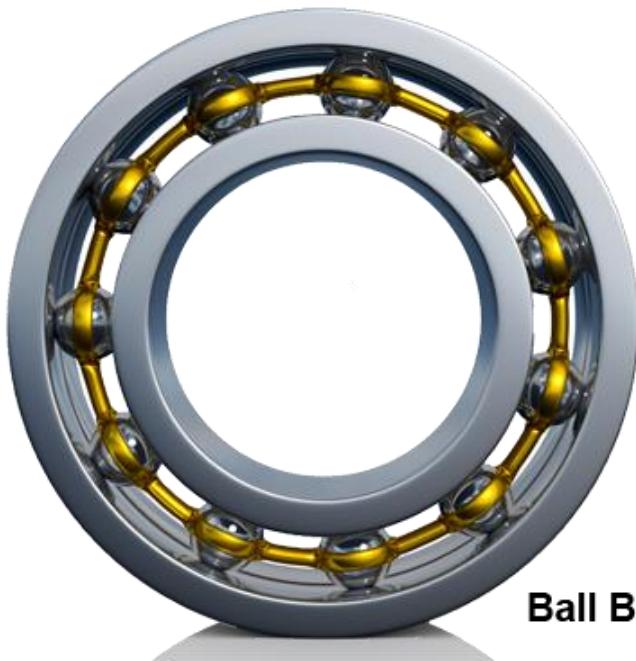
# Armature & Commutator



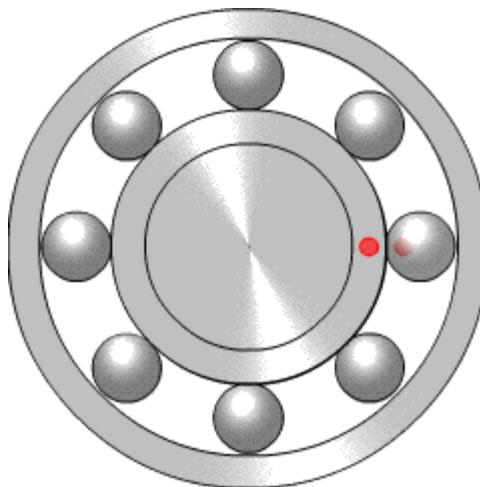
# Brushes



# Bearings

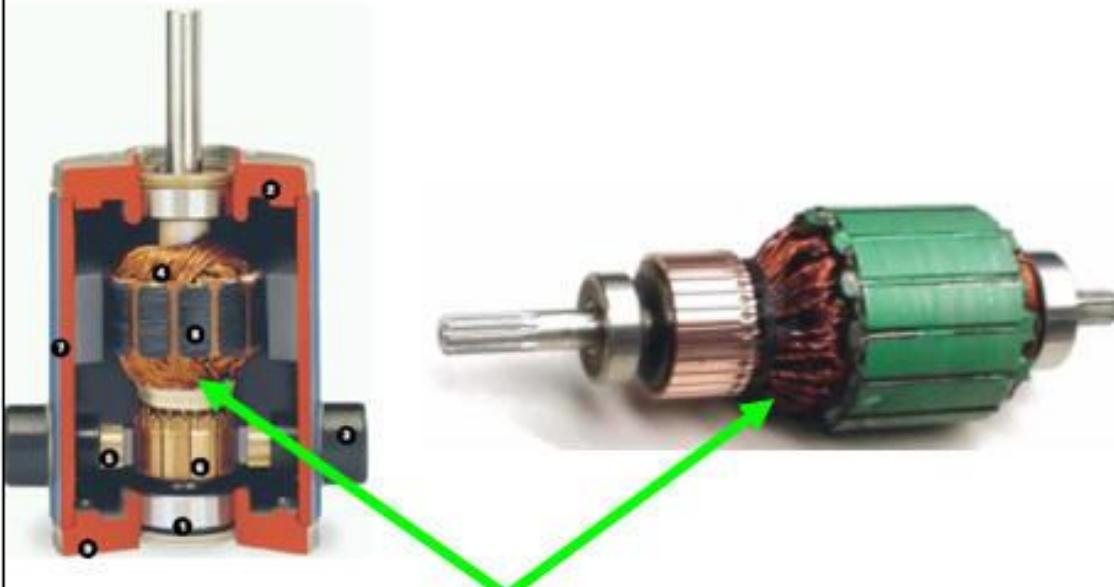


**Ball Bearing**



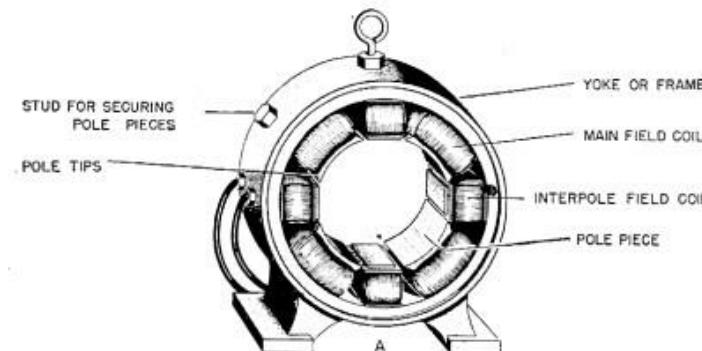
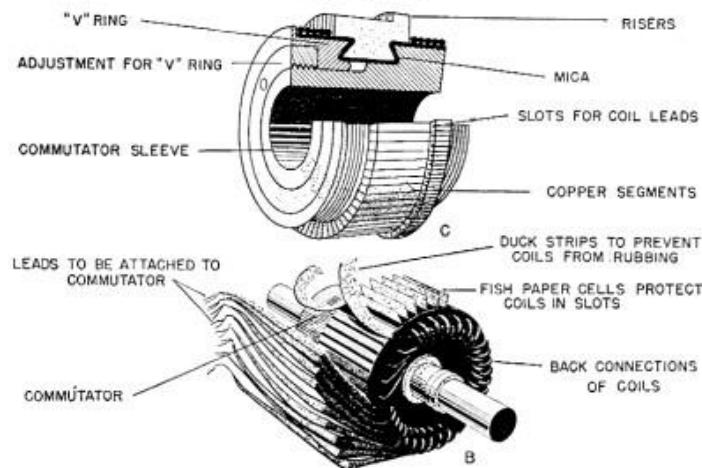
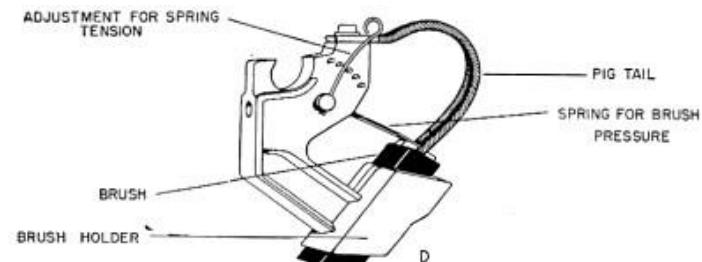
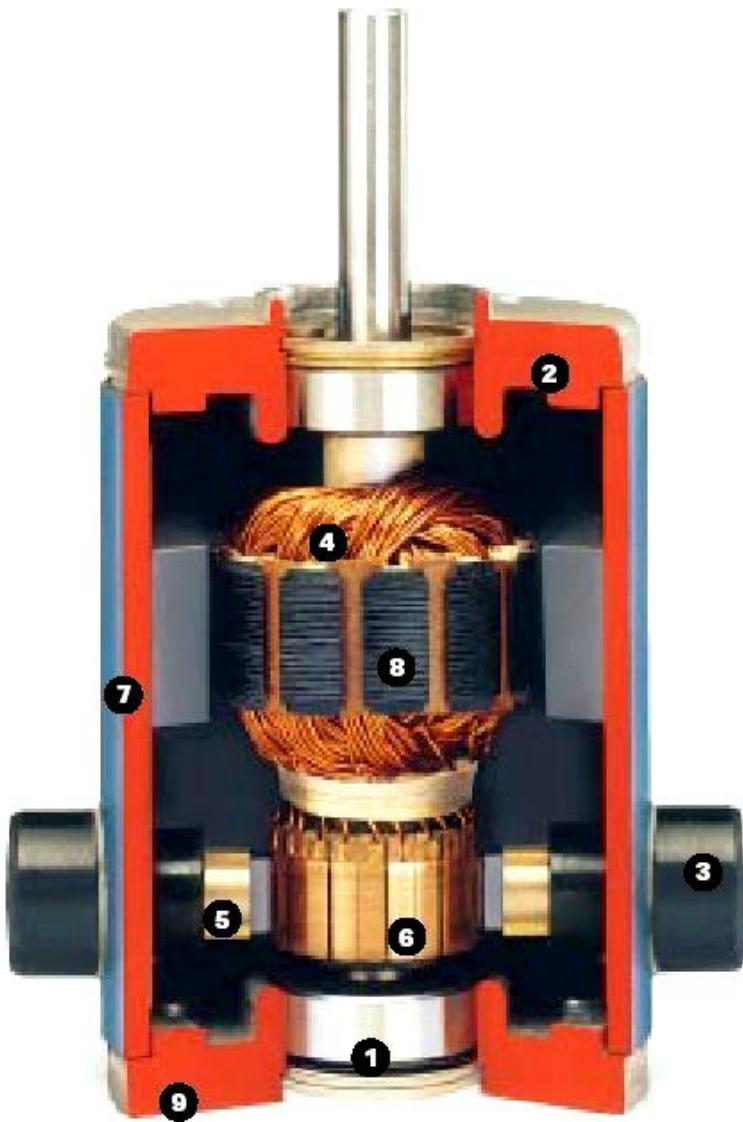
# Shaft

The Armature of a DC Permanent Magnet Motor



Magnet Field Windings Act as Heaters

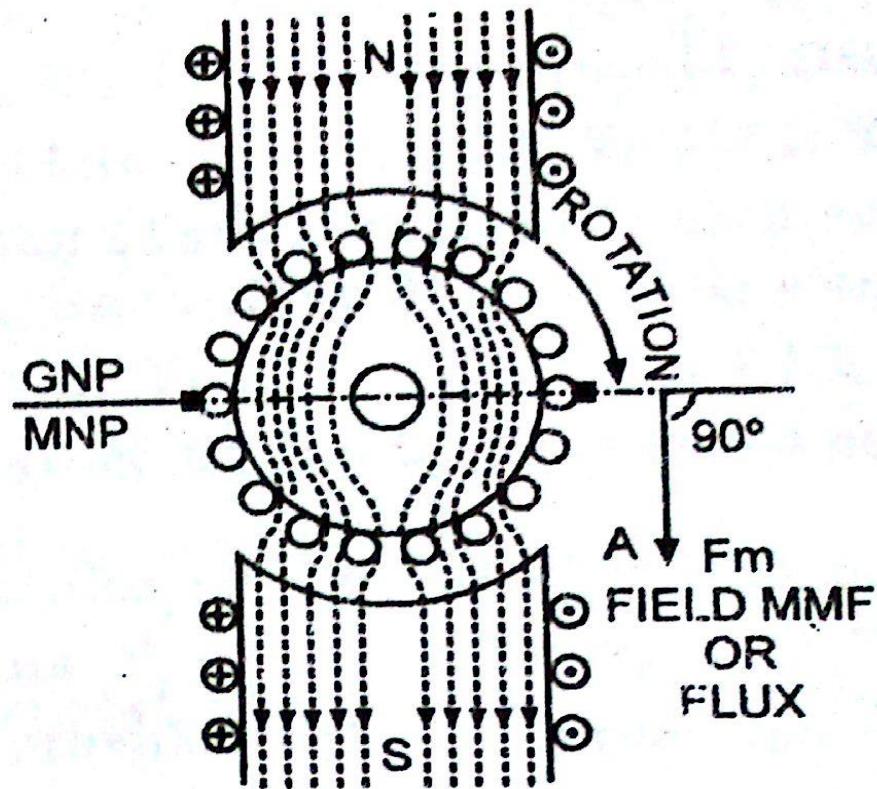
*Copyright @2008 pedalpowergenerator.com*



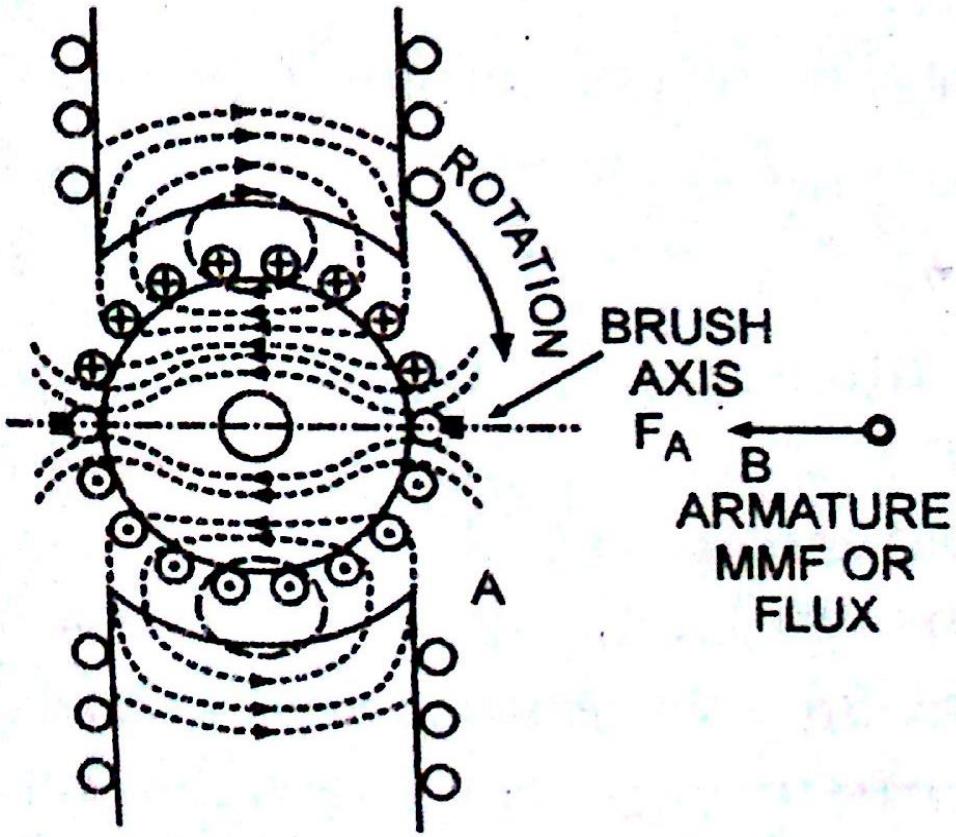
# **Armature Reaction**

# **DC Machine: Armature Reaction**

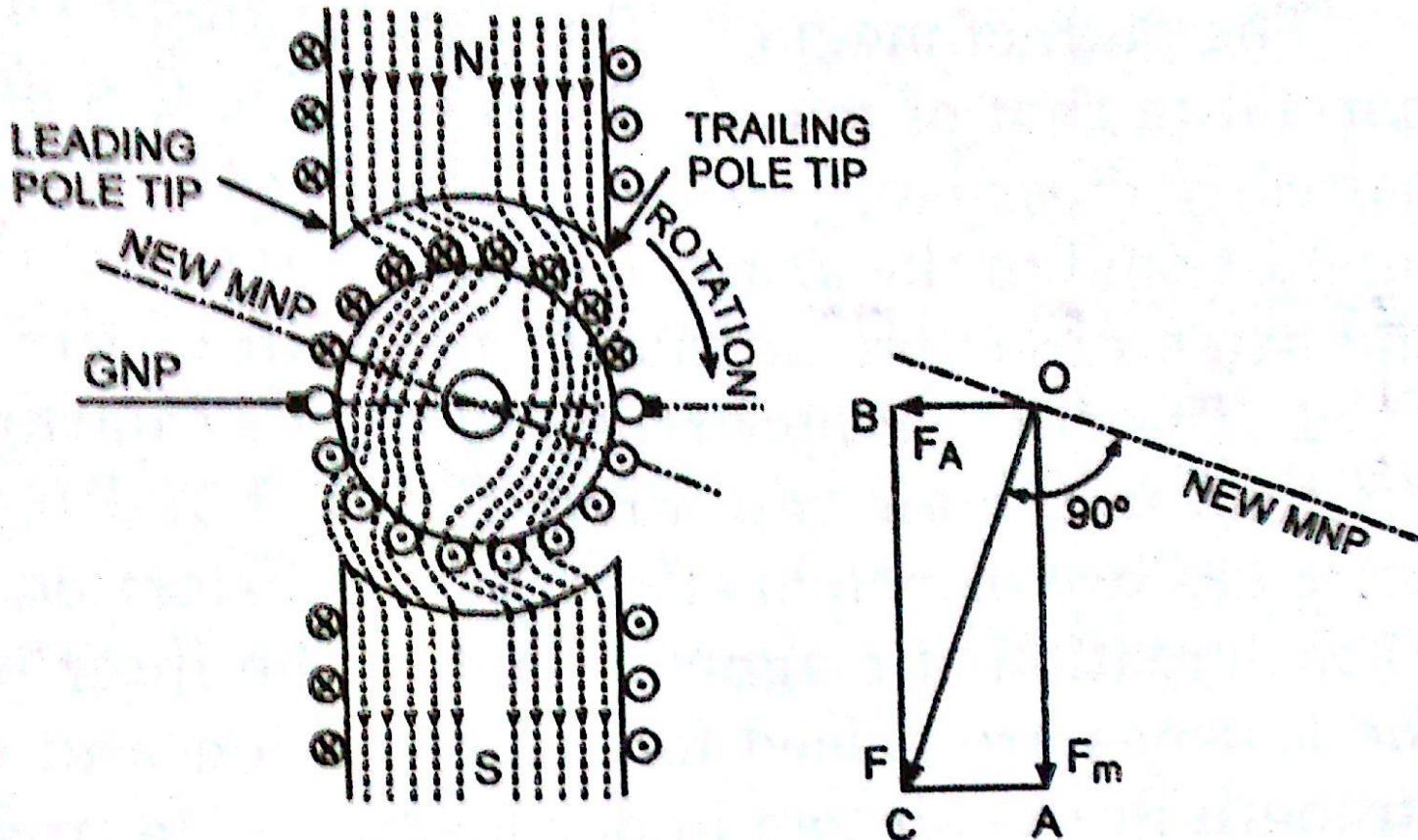
**The effect of magnetic field set up by the armature current on the distribution of flux under the main poles of a DC machine is known as Armature Reaction**



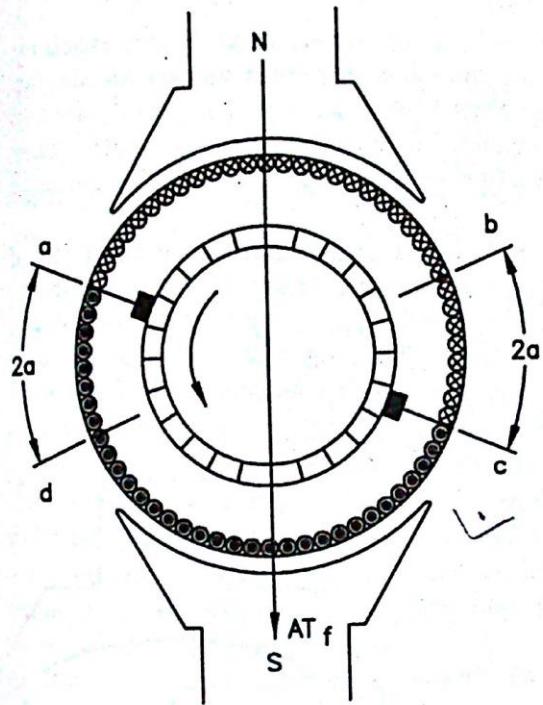
*Distribution of Flux Due To Main Poles  
When Generator is Supplying No Load*



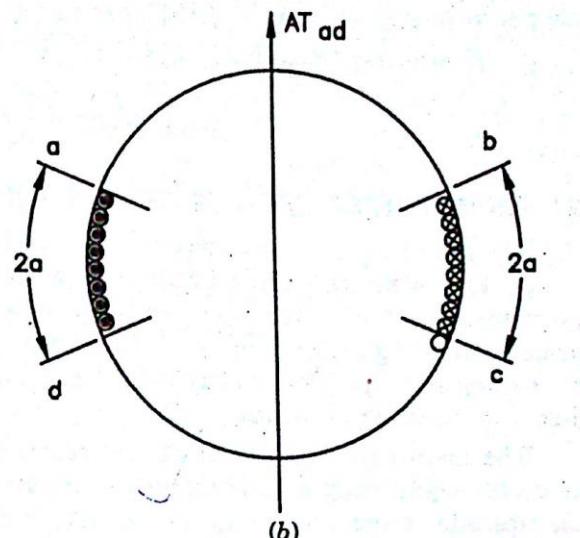
*Distribution of Flux Due To Armature  
Current Carrying Conductors While Field  
Coils Carrying No Current*



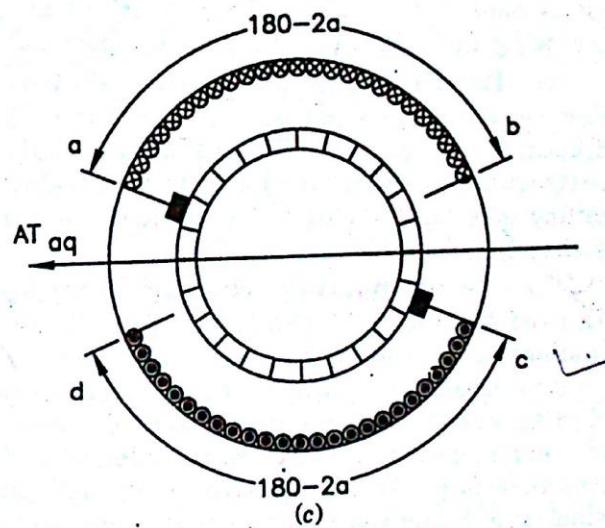
*Distribution of Resultant Flux Established From  
Simultaneous Action of Field and Armature Current*



(a)



(b)



(c)

Fig. 9.31. Distribution of armature current with brush shift.

# Demagnetizing MMF/Pole

$$\begin{aligned}AT_{ad} &= AT_a \times \frac{2\alpha}{180} \\&= \left(\frac{I_a}{a}\right) \left(\frac{Z}{2p}\right) \left(\frac{2\alpha}{180}\right) \\&= \frac{I_a Z}{ap} \left(\frac{\alpha}{180}\right)\end{aligned}$$

## Cross-magnetizing MMF/Pole

$$AT_{aq} = AT_a - AT_{ad}$$

$$= AT_a \left( 1 - \frac{2\alpha}{180} \right)$$

$$= \frac{I_a Z}{2ap} \left( 1 - \frac{2\alpha}{180} \right)$$

# Effects of Armature Reaction

- Reduction in total flux
  - Decrease in generated EMF: Generator
  - Decrease in Torque: Motor
- More Iron Losses at Full load than No load
- Commutation
  - Sparking
  - Delayed Commutation

# **Reduction of Effects of Armature Reaction**

- Increase in length of Airgap at pole tips
- Increasing in reluctance of pole tips
- Interpoles
- Compensating Windings

# Increase in length of Airgap at pole tips

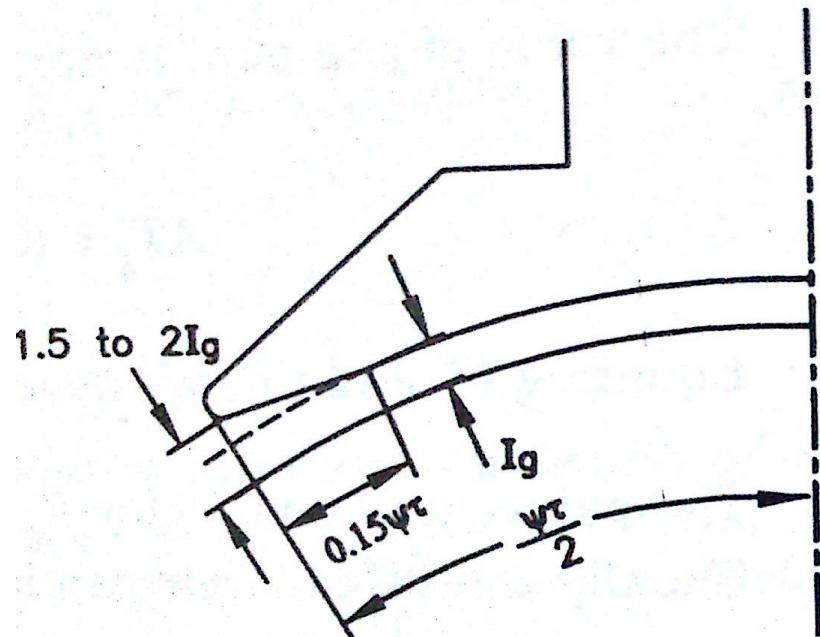
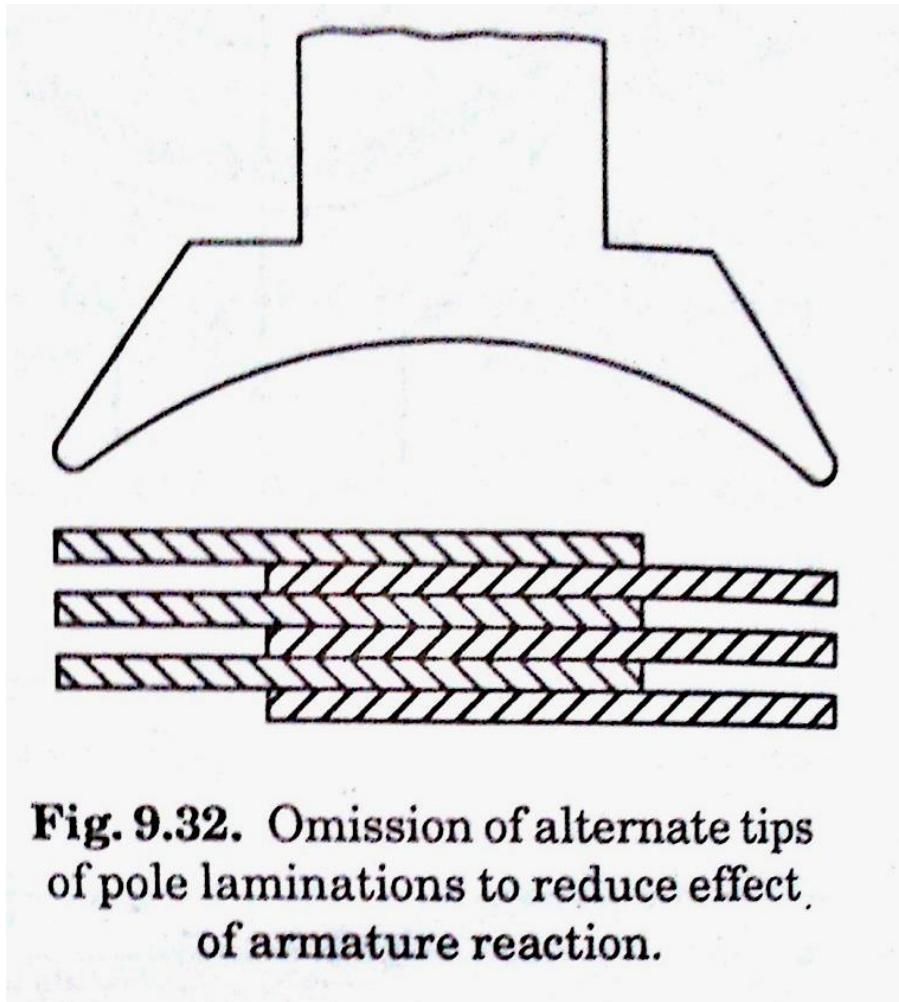


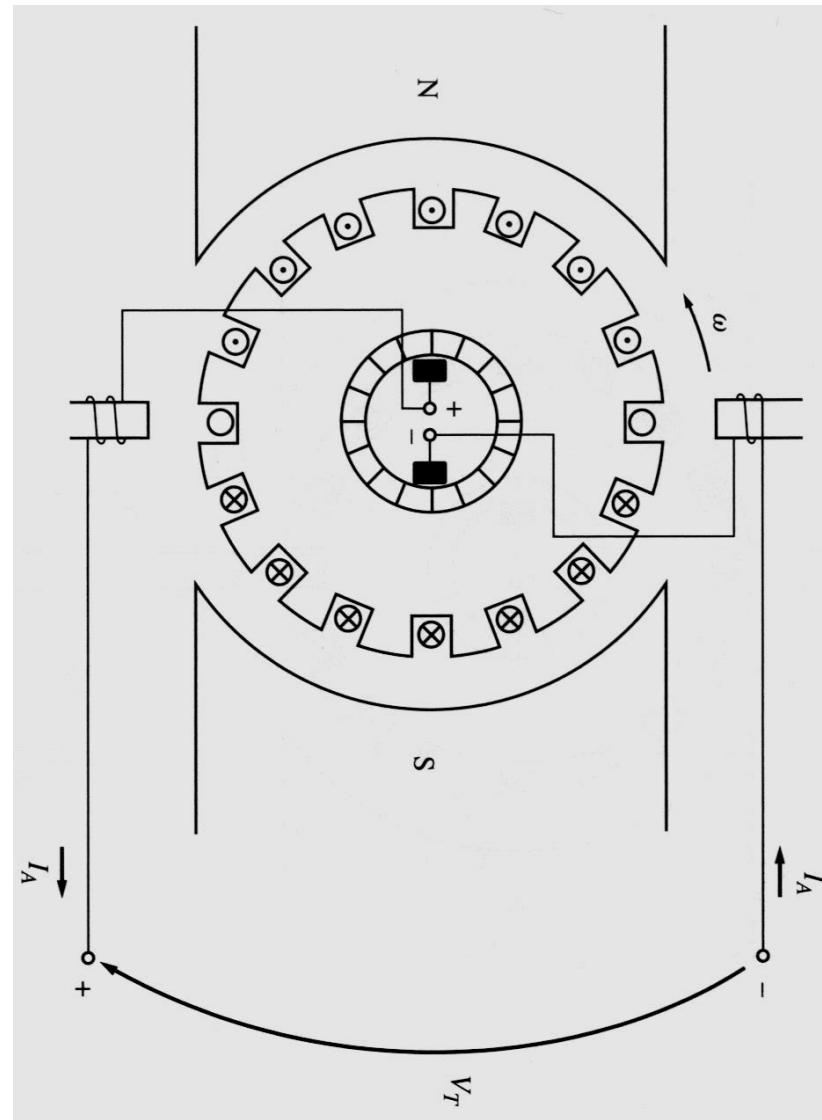
Fig. 9.27. Profile and chamfering of pole face.

# Increasing in reluctance of pole tips

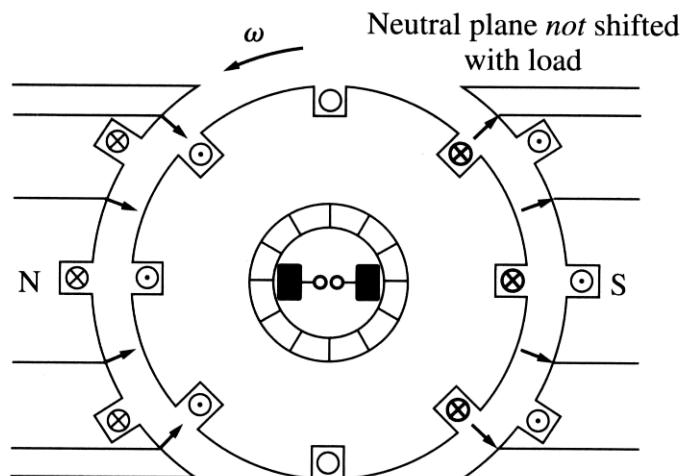
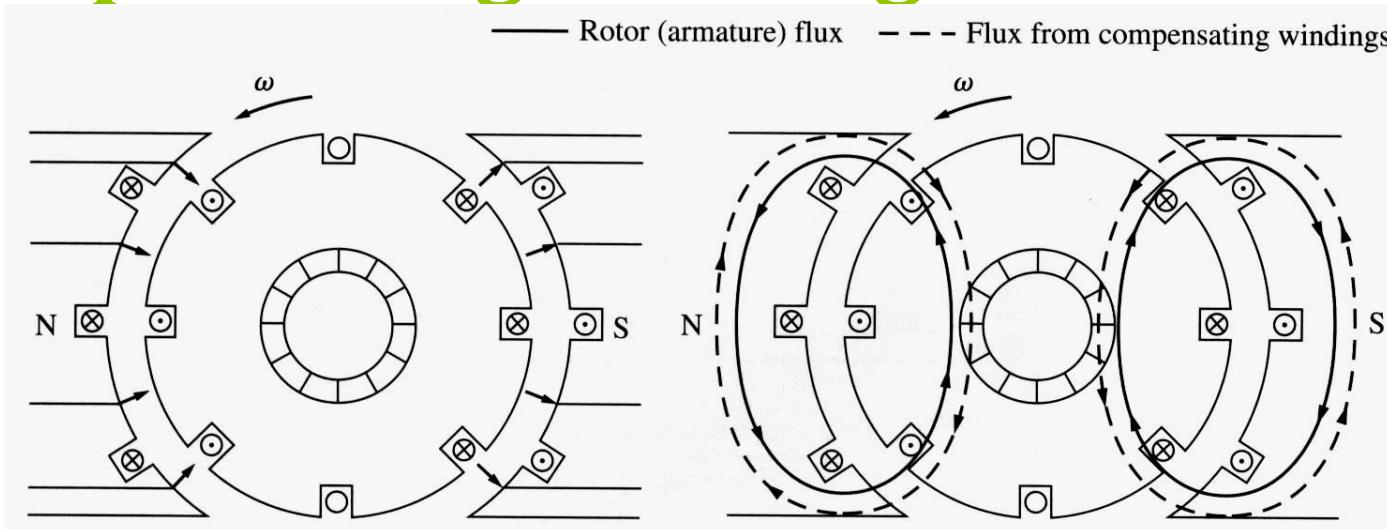


**Fig. 9.32.** Omission of alternate tips of pole laminations to reduce effect of armature reaction.

# Inter Poles



# Compensating Windings



# Armature Winding:

- Single turn coil
- Multi turn coil

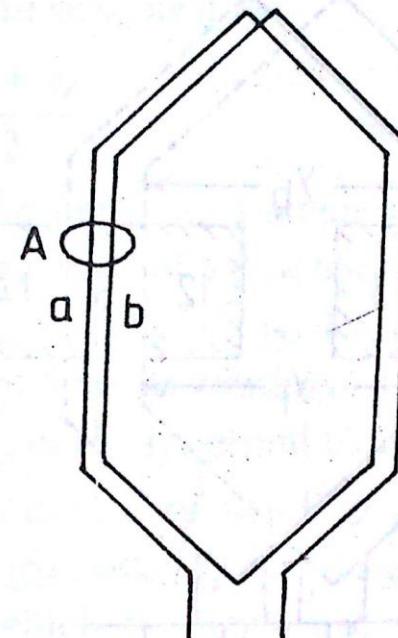
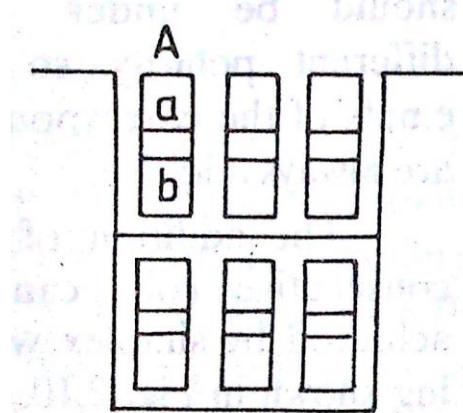
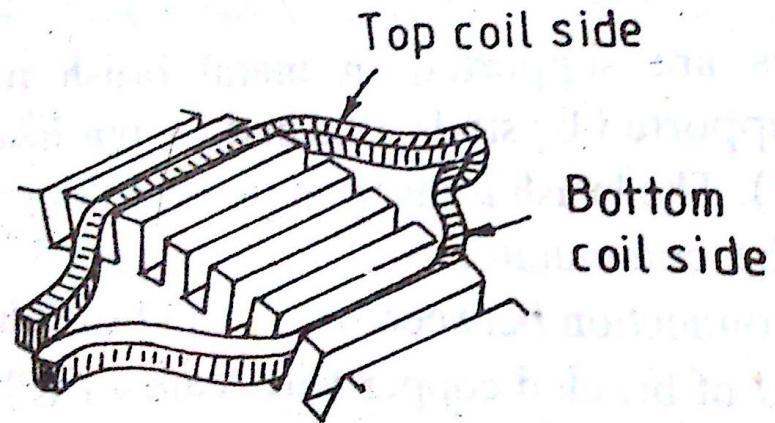


Fig. 2.7. Arrangement of conductors in a slot and a 2 turn coil.

# Armature Windings

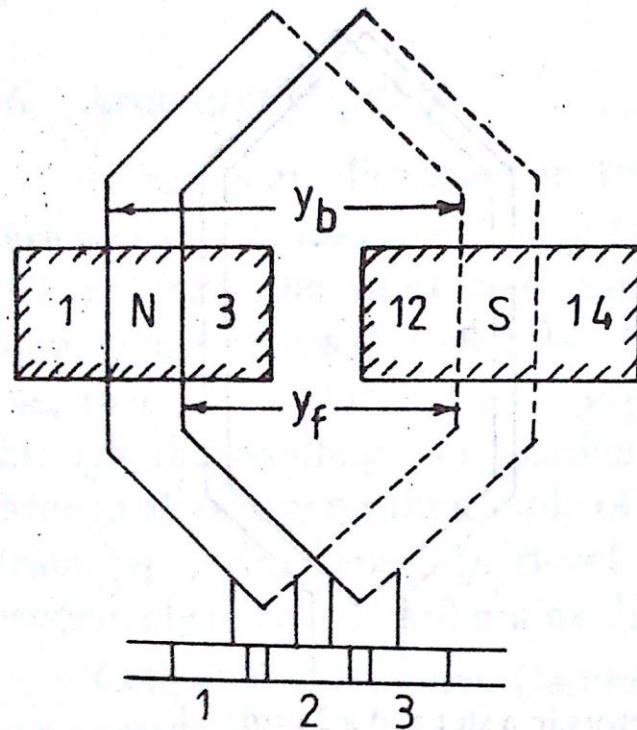


Fig. 2.9. Simplex lap winding.

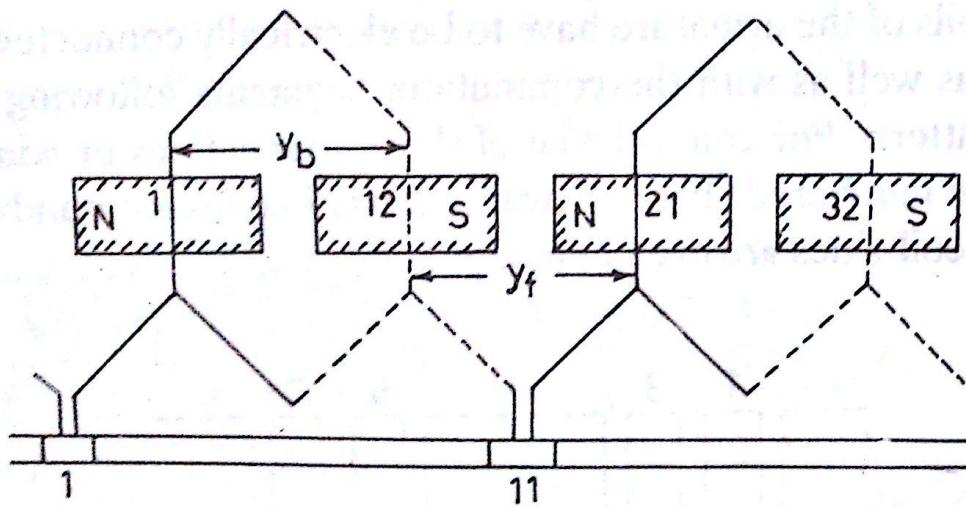
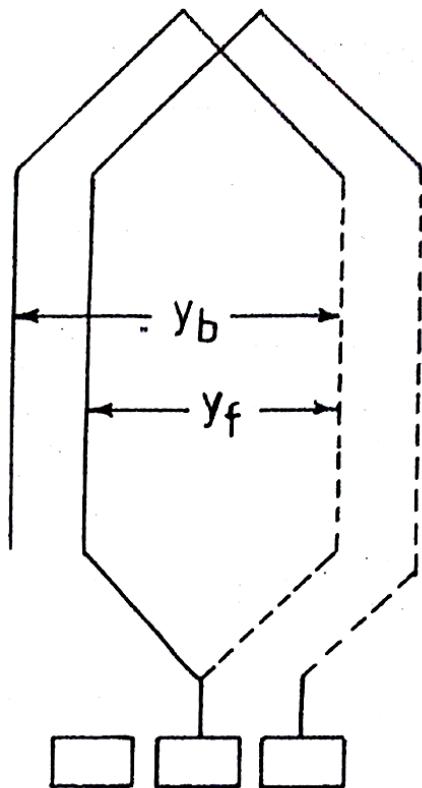


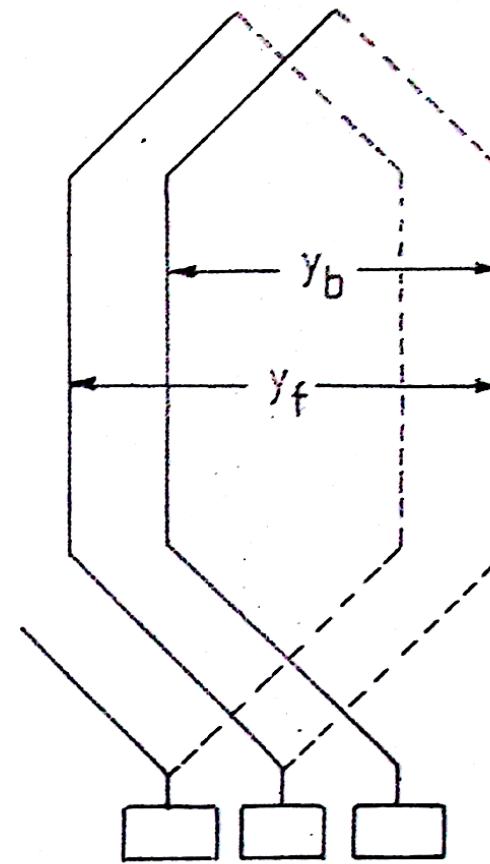
Fig. 2.10. Simplex wave winding.

# Armature Windings



(a) Progressive

Fig. 2.11. Progressive and retrogressive simplex lap winding.



(b) Retrogressive

# Armature Windings

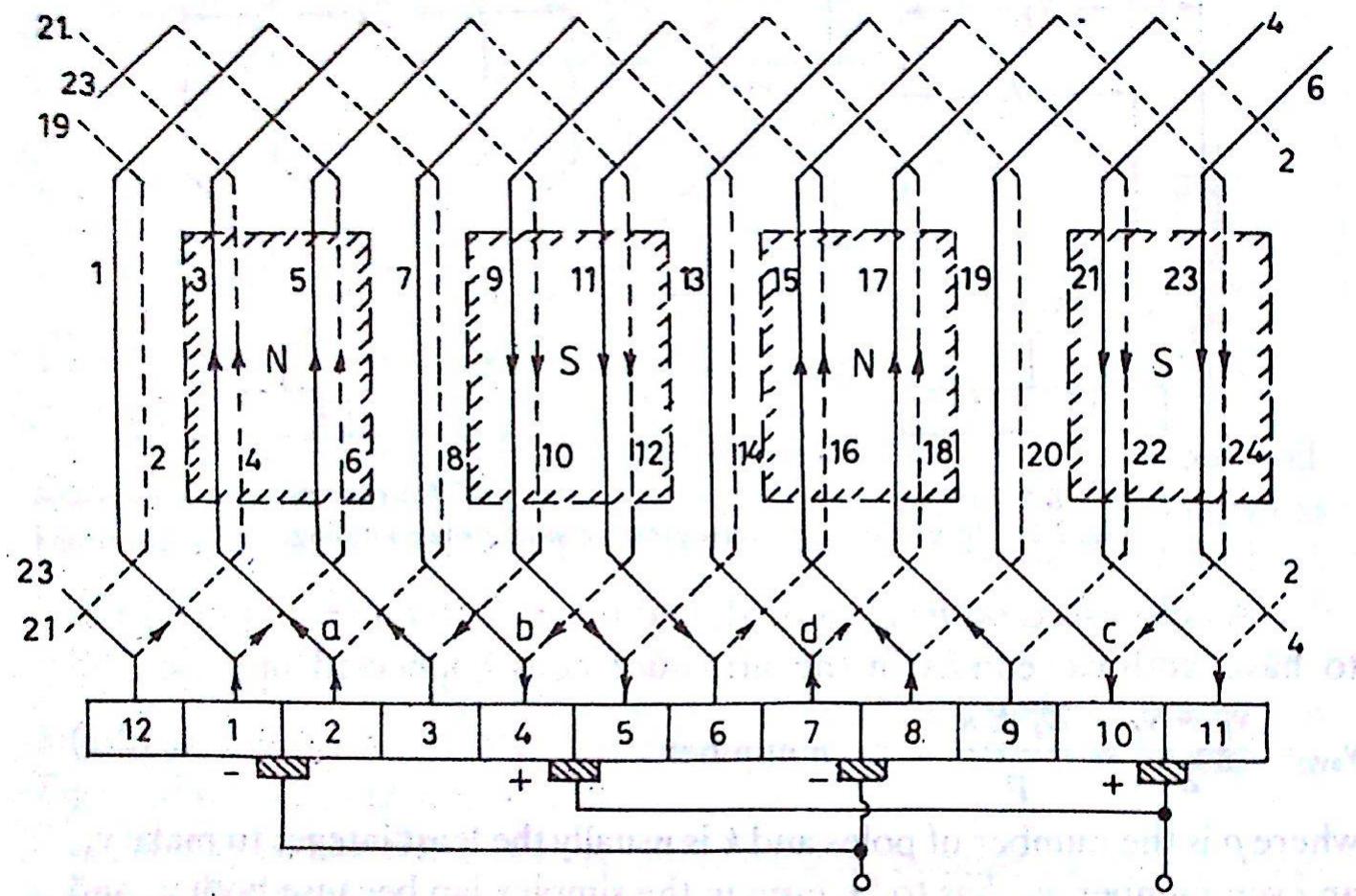


Fig. 2.12. Developed view of 4-pole, 12-coils simplex lap winding.

# Armature Windings

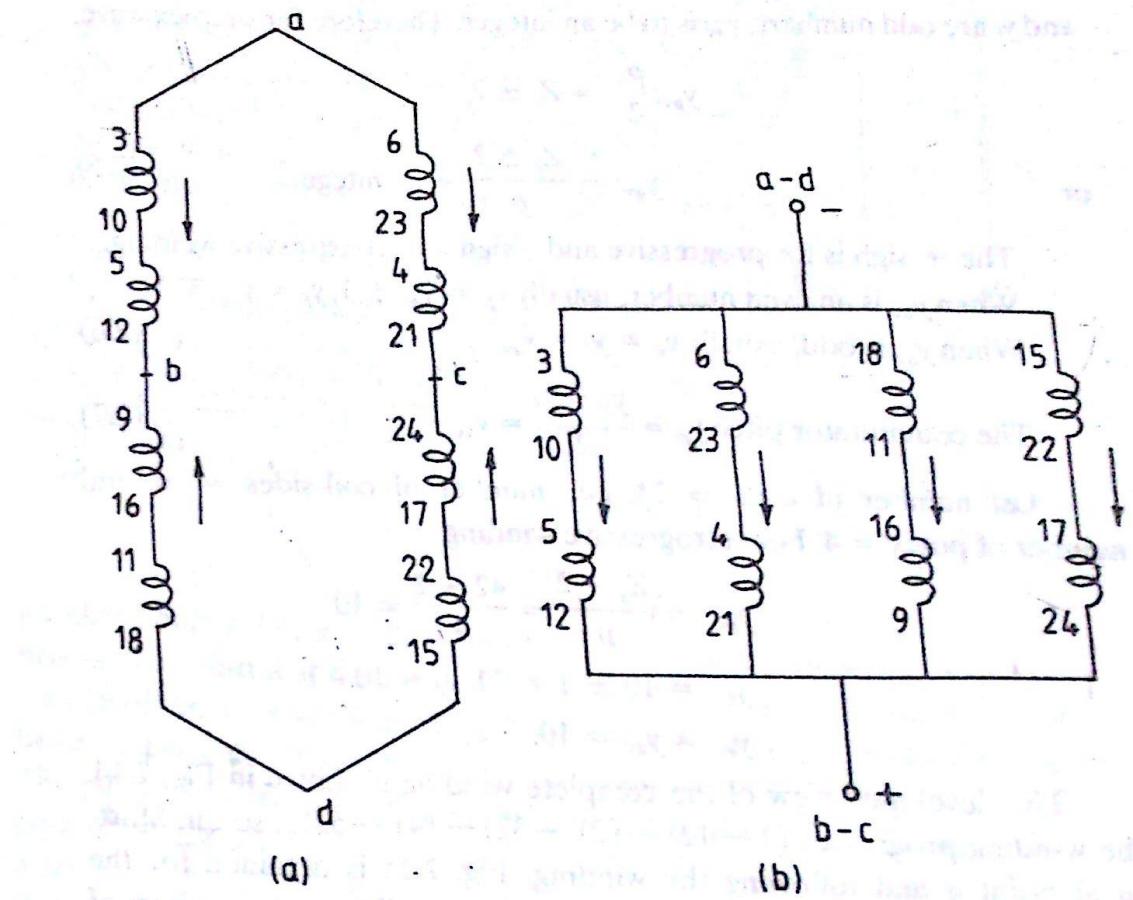
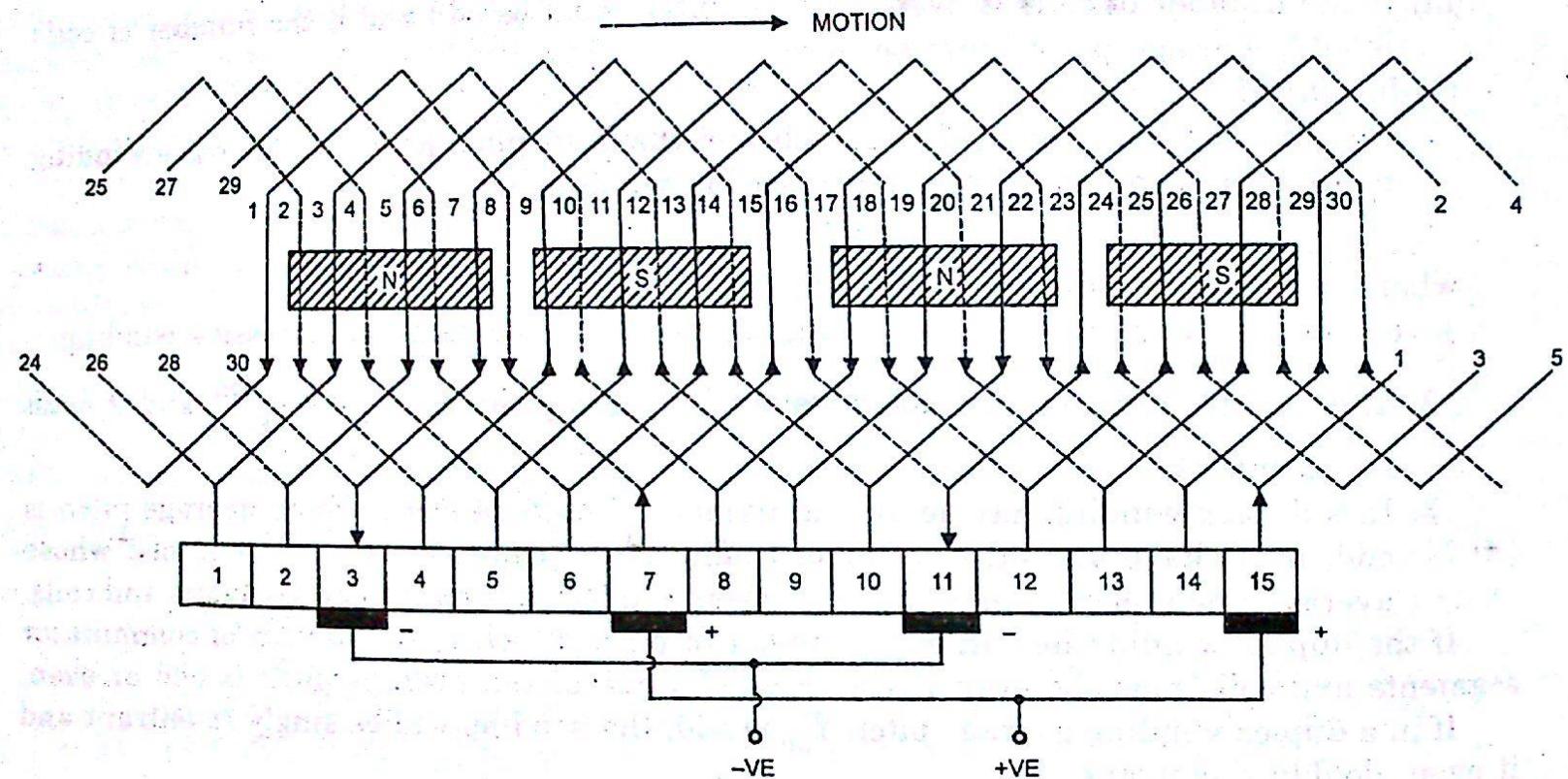


Fig. 2.13. Sequence of induced e.m.fs in conductors and four parallel circuits of the winding of Fig. 2.12.

# Armature Windings



Developed View of 4-pole, Double Layer, Simplex Wave Winding With 30 Coil Sides

Fig. 4.30

## Lap Winding

$$Y_b \approx \frac{Z}{P}$$

$$Y_b = Y_f \pm 2m$$

$$Y_{av} = \frac{Y_b + Y_f}{2}$$

$$Y_c = m$$

## Wave Winding

$$Y_b \approx \frac{Z}{P}$$

$$Y_b = Y_f \pm 2$$

$$Y_{av} = \frac{Y_b + Y_f}{2}$$

$$Y_c = Y_{av}$$

# Choice of Armature Winding

Lap Winding	Wave Winding
A=P, Less current in each path	A=2, Each path carries half current
Low voltage, high current	High voltage, Low current
Equalizer connection required	Equalizer connection not required
Precise placing of brush	Independent

# Commutation

# Commutation

- Process of converting generated alternating current to externally available direct current.
- Reversal of current in armature coil by means of brush and commutator bars is called *commutation process*.
- Time period during which coil remains short circuited is called *commutation period*.

# Good Commutation

- Current in a coil should be completely reversed
- No sparking at brushes
- No damage to commutator surface

# Poor Commutation

## ○ Mechanical Conditions

- Uneven commutator surface
- Non-uniform brush pressure
- Vibration of brushes in holder

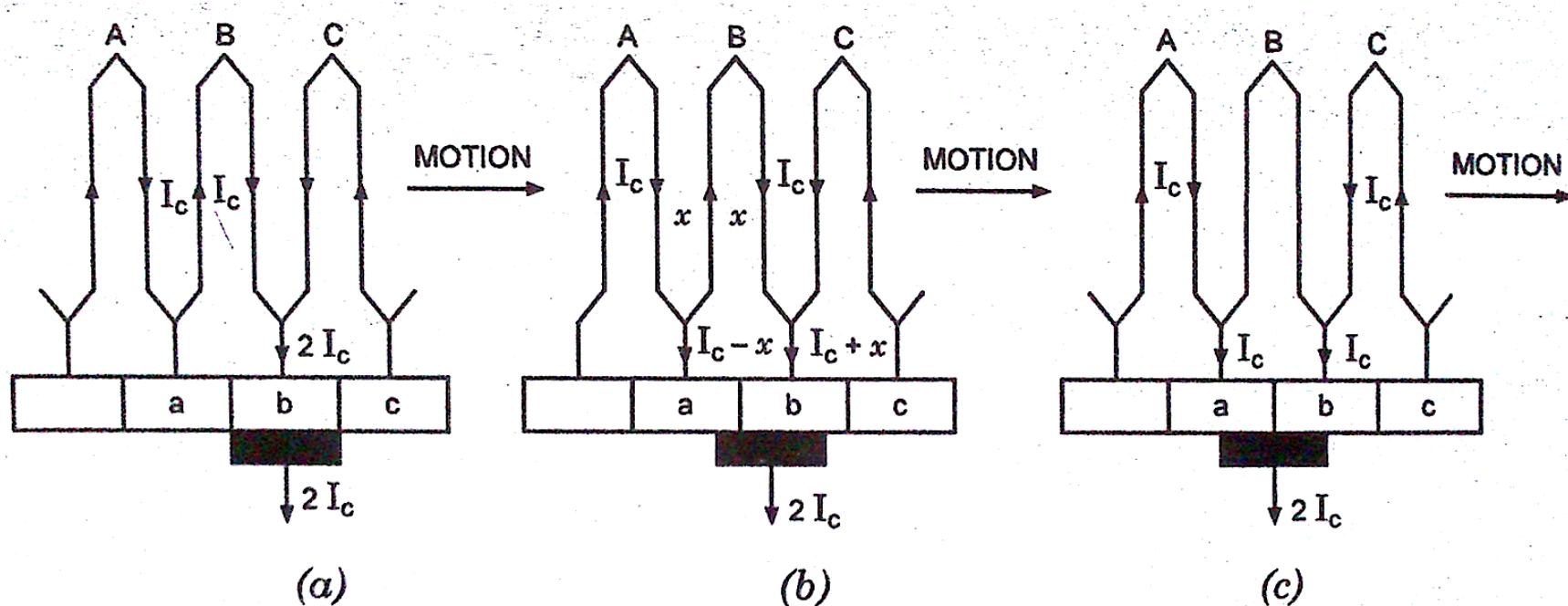
## ○ Electrical conditions

- Increase in voltage between two adjacent commutator segments
- Increase in current density at trailing edge of brush
- Armature reaction & Armature leakage flux

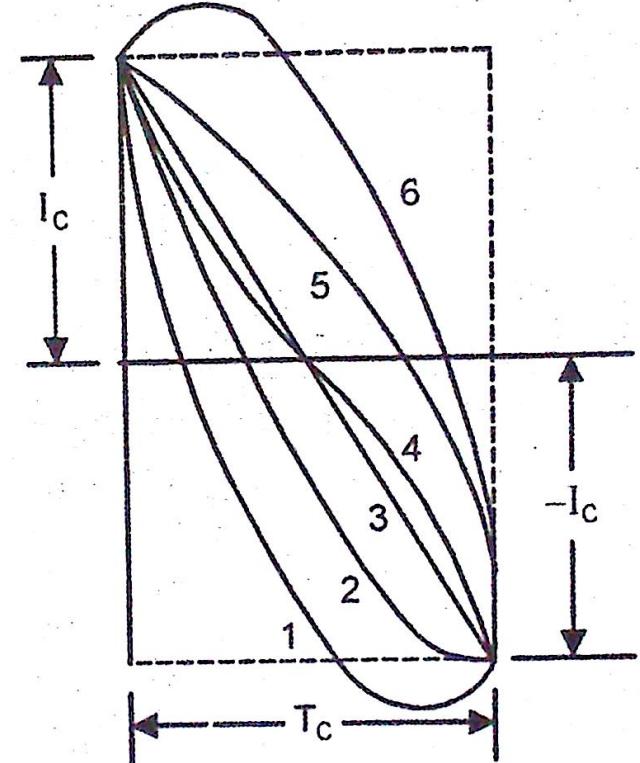
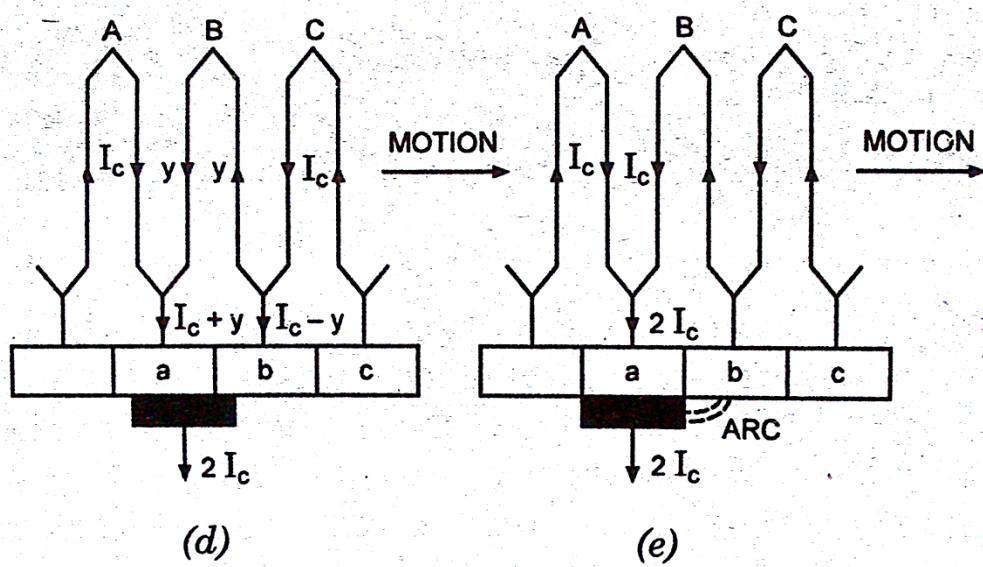
# Effects of Poor Commutation

- Sparking
- Overheating at brush-commutator contact
- Damages to brush & commutator surface
- Damage to brush, increase sparking progressively worse

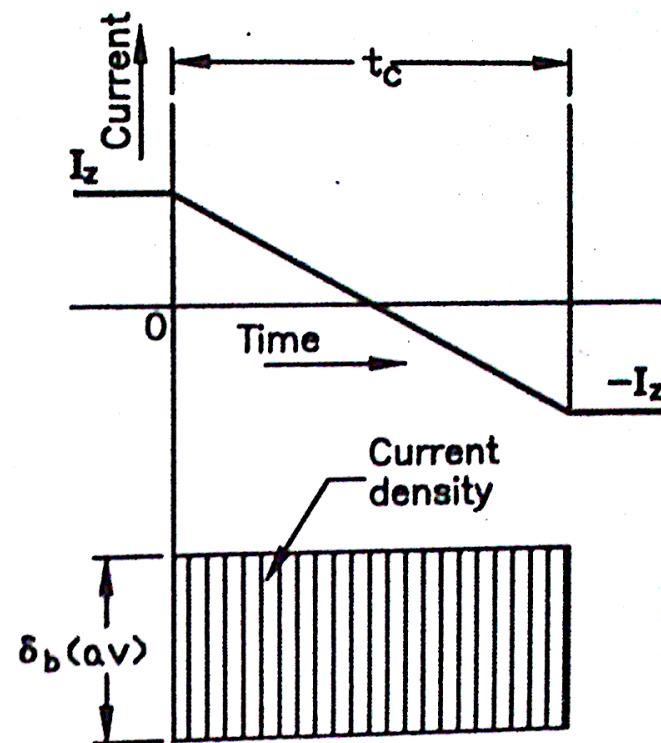
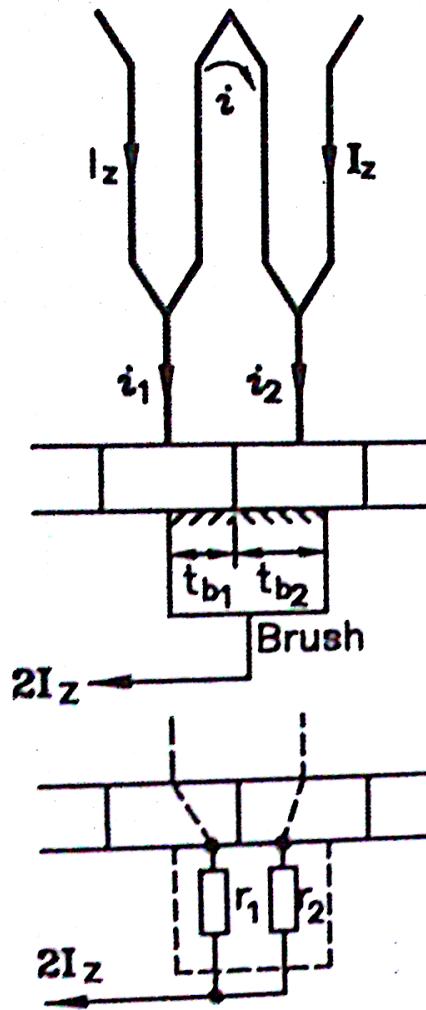
# Commutation Process



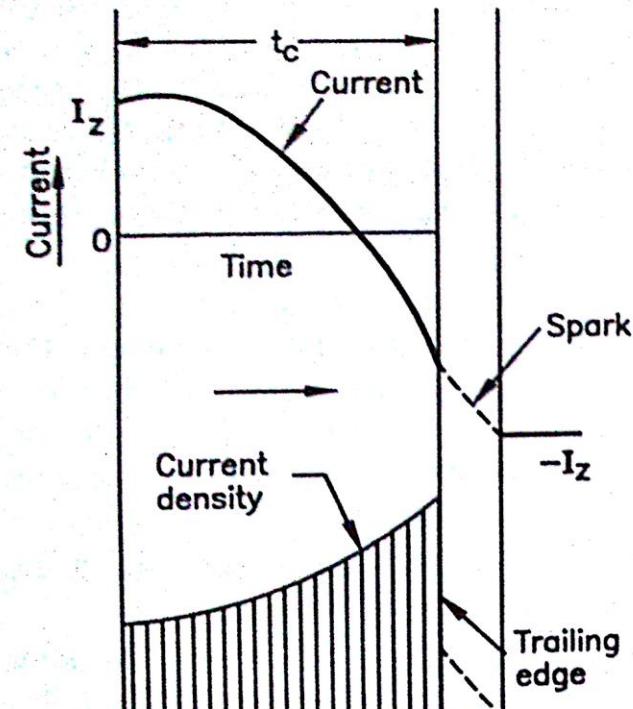
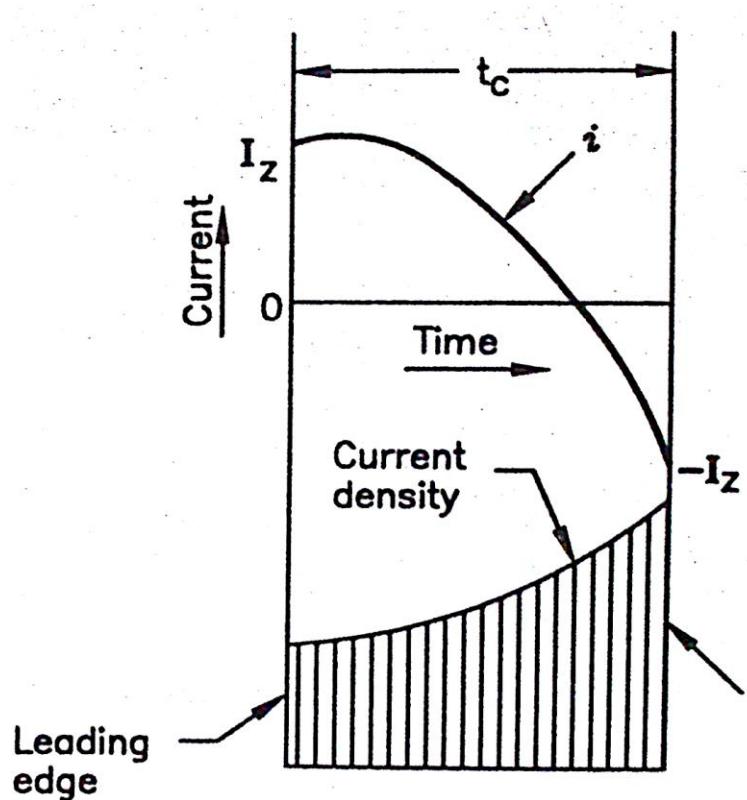
# Commutation Process



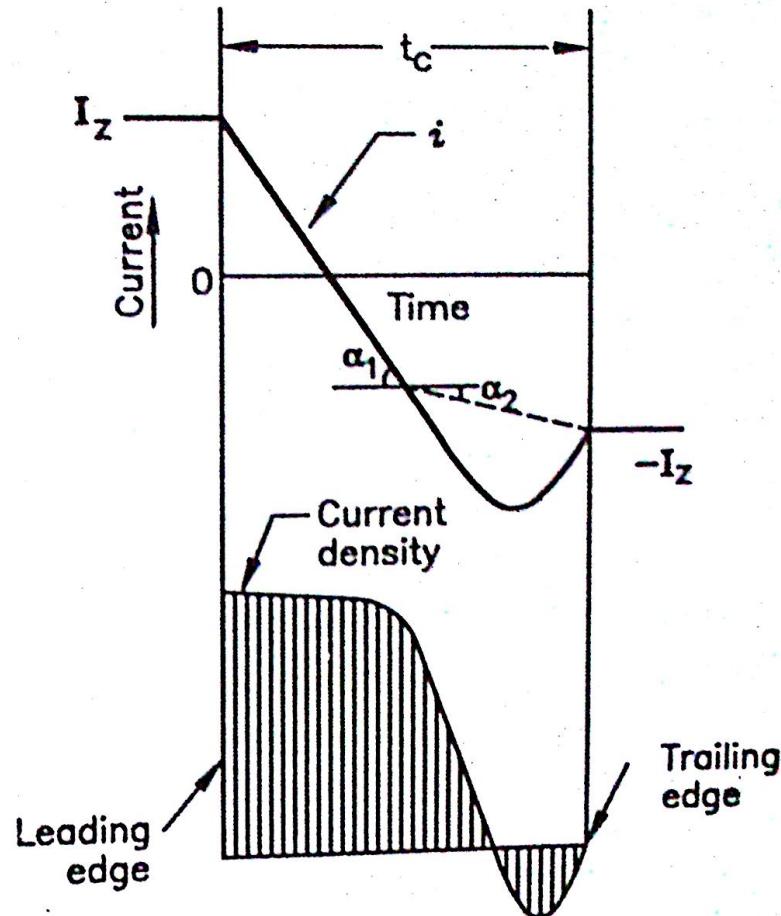
# Straight Line Commutation



# Retarded Commutation



# Accelerated Commutation



# Reactance Voltage (Pitchelmayer's Equation)

Inductance of coil =  $2T_c^2 L \lambda$

Reactance Voltage

$$E_{rav} = L \frac{di}{dt}$$

$$E_{rav} = 2T_c^2 L \lambda \times \frac{2I_z}{\tau_c}$$

$$\tau_c = t_c = \frac{\beta_c}{V_c} = \frac{\pi D_c}{C} \times \frac{1}{\pi D_c n} = \frac{1}{Cn}$$

# Reactance Voltage (Pitchelmayer's Equation)

$$E_{rav} = 2T_c^2 L \lambda \times 2I_z Cn = 2T_c L \lambda I_z Zn$$

$$\therefore 2CT_c = Z$$

$$E_{rav} = 2T_c L \lambda \left( I_z \frac{Z}{\pi D} \right) \pi D n$$

$$E_{rav} = 2T_c L \lambda ac V_a$$

# Flux Density under Interpole Shoe

$B_{ci}$  = Flux density under interpole shoe

$L_{ip}$  = Length of interpole

$E_{gi}$  = Voltage generated in a coil by  
interpole field

$T_c$  = No. of coil turns

$\lambda$  = Specific permeance

# Flux Density under Interpole Shoe

$B_{ci}$  = Flux density under interpole shoe

$E_{gi} = 2 \times T_c \times$  Voltage generated in each condt.

$$E_{gi} = 2T_c B_{gi} L_{pi} V_a$$

$$E_{rav} = \frac{4T_c \lambda L I_z Z_s}{T_c}$$

$$\frac{4T_c \lambda L I_z Z_s}{T_c} = 2T_c B_{gi} L_{pi} V_a$$

$$B_{gi} = 2I_z Z_s \frac{L}{L_{ip}} \frac{1}{V_a T_c} \lambda$$

# Design of Interpole Winding

$l_{gi}$  = Length of airgap under interpole shoe

$K_{gi}$  = Interpole gap contraction factor

$$AT_a = \frac{I_z Z}{2 p}$$

MMF required to establish  $B_{gi} = 800000B_{gi}K_{gi}l_{gi}$

MMF required to overcome armature reaction =  $\frac{I_z Z}{2 p}$

Interpole MMF  $AT_i = 800000B_{gi}K_{gi}l_{gi} + \frac{I_z Z}{2 p}$

No. of Interpole Turns =  $\frac{AT_i}{I_a}$

# Thank You