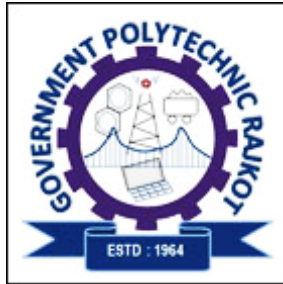


Utilization of Electrical Energy 3340903



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Unit – 4

Electric Traction

UTILIZATION OF ELECTRICAL ENERGY

Topics

- **Requirements of ideal Traction System**
- **Traction Mechanics: Types of Services, Speed Time Curve**
- **Supply system: DC System, Composite System, Single Phase ac system with low and normal frequency and 3 phase system**

Requirement of Ideal Traction System

- **High Starting Torque**
- **Self Contained**
- **Simple Speed Control**
- **Smooth Acceleration & Retardation**
- **High Overload Capacity**
- **Compact In Size**
- **Low Maintenance**
- **High Efficiency**
- **No Interference to Communication Lines**
- **Long Life**
- **Low Cost**
- **Pollution Free**

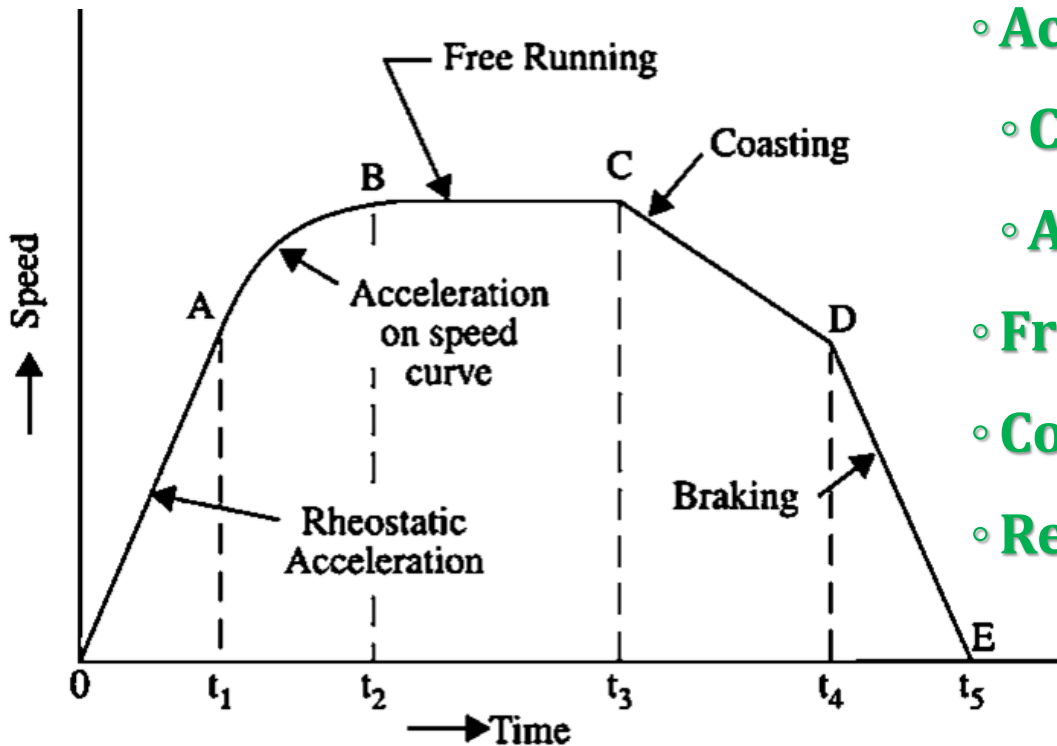
Traction Mechanics

- **Speed Time Curve**

- **Types of Services**

Speed – Time Curve

- The curve drawn between Speed v/s Time, taking Speed (km/hr) on Y-axis and Time (second or Minute) on X-axis, is known as Speed-Time Curve.

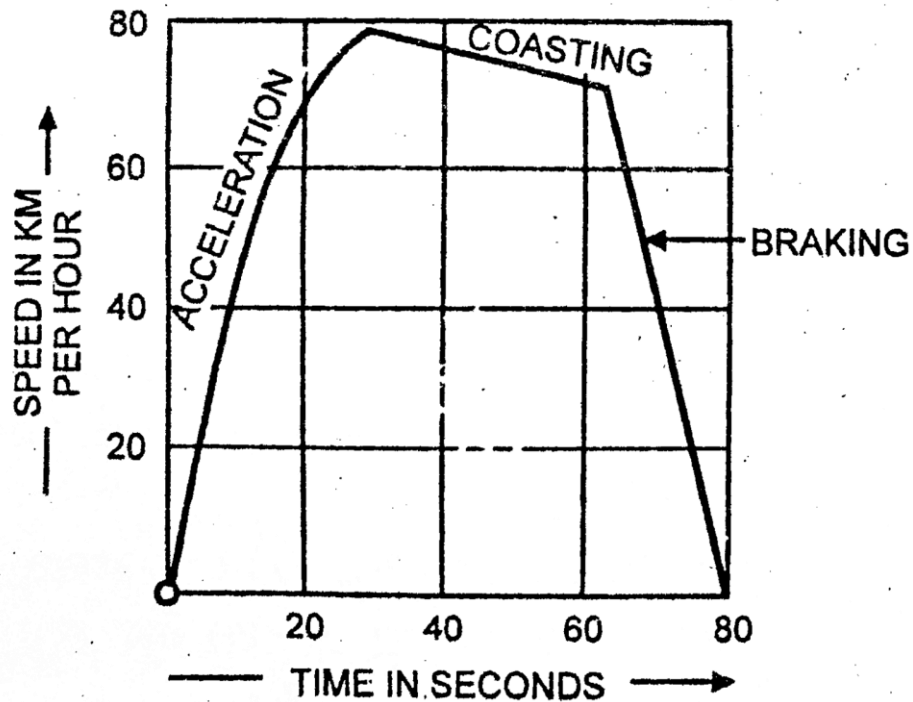


- **Acceleration**
- **Constant Acceleration**
- **Acceleration on speed curve**
- **Free Running**
- **Coasting**
- **Retardation (Braking)**

Speed – Time Curve

◦ Typical Speed – Time Curves

Urban/City Service

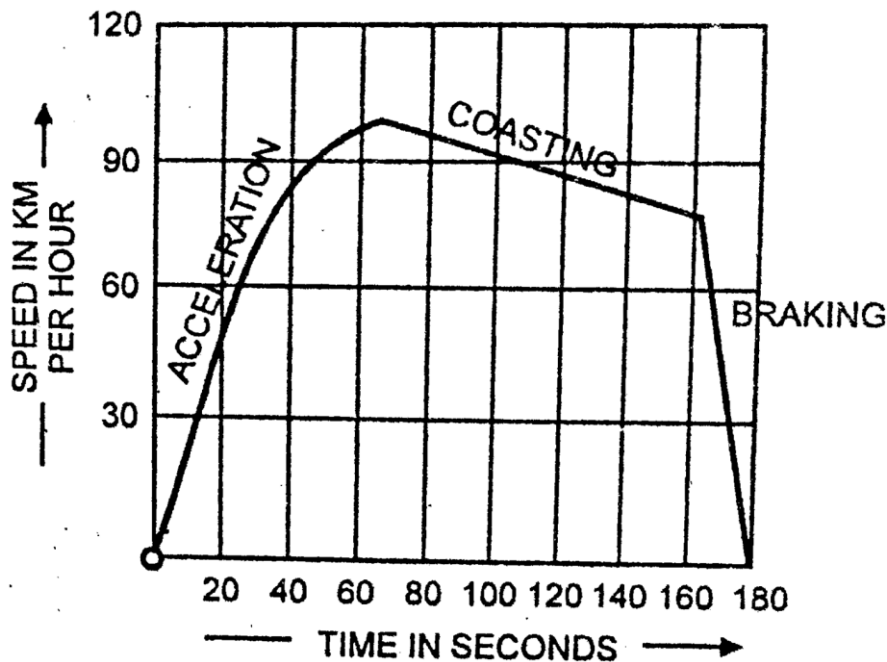


- **Distance between two stops:**
Short (about 1km)
- **Acceleration:**
1.5 – 4 km/h/sec
- **Retardation:**
3 – 4 km/h/sec
- **Coasting Period:**
Short
- **Free Running:**
NA

Speed – Time Curve

◦ Typical Speed – Time Curves

Suburban Service



◦ Distance between two stops:

1 – 8 km

◦ Acceleration:

1.5 – 4 km/h/sec

◦ Retardation:

3 – 4 km/h/sec

◦ Coasting Period:

Comparatively long

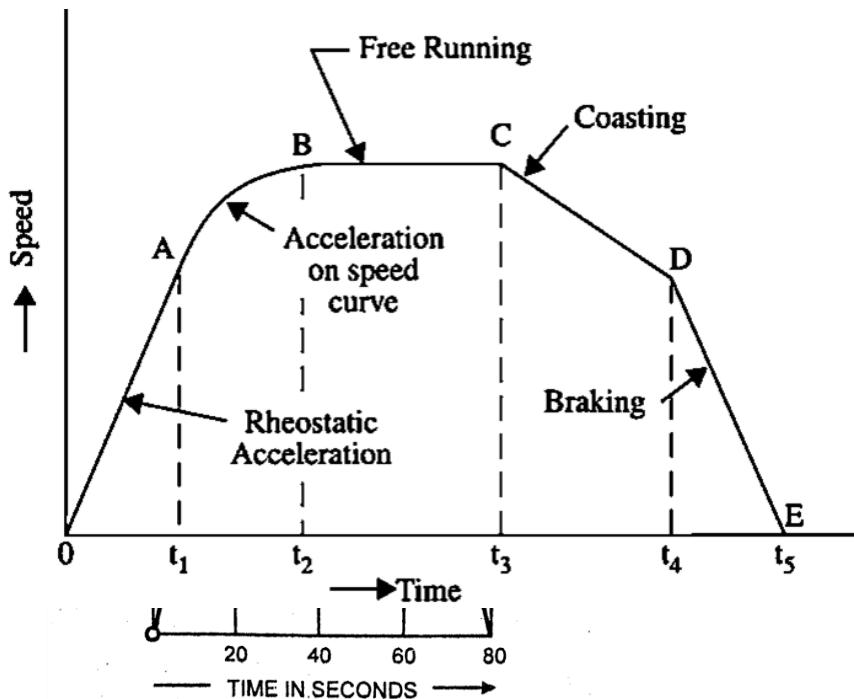
◦ Free Running:

NA

Speed – Time Curve

◦ Typical Speed – Time Curves

Main Line Service



◦ **Distance between two stops:**

More than 10 km

◦ **Acceleration:**

0.6 – 0.8 km/h/sec

◦ **Retardation:**

1.5 km/h/sec

◦ **Coasting Period:**

◦ **Long**

◦ **Free Running:**

Long

Terms related to Speed – Time Curve

◦ Crest Speed:

The maximum speed attained by the vehicle during the run is known as Crest Speed.

$$\text{Average Speed} = \frac{\text{Distance between stops}}{\text{Actual time of run}}$$

◦ Average Speed:

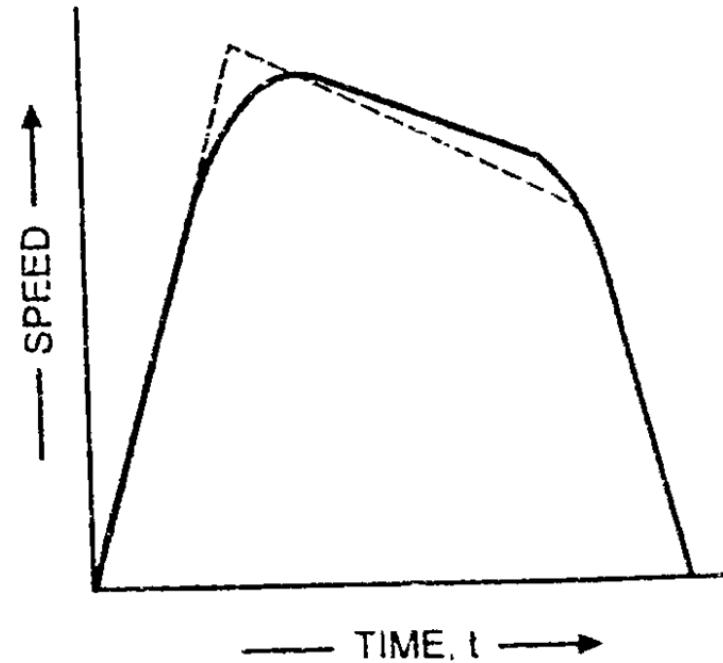
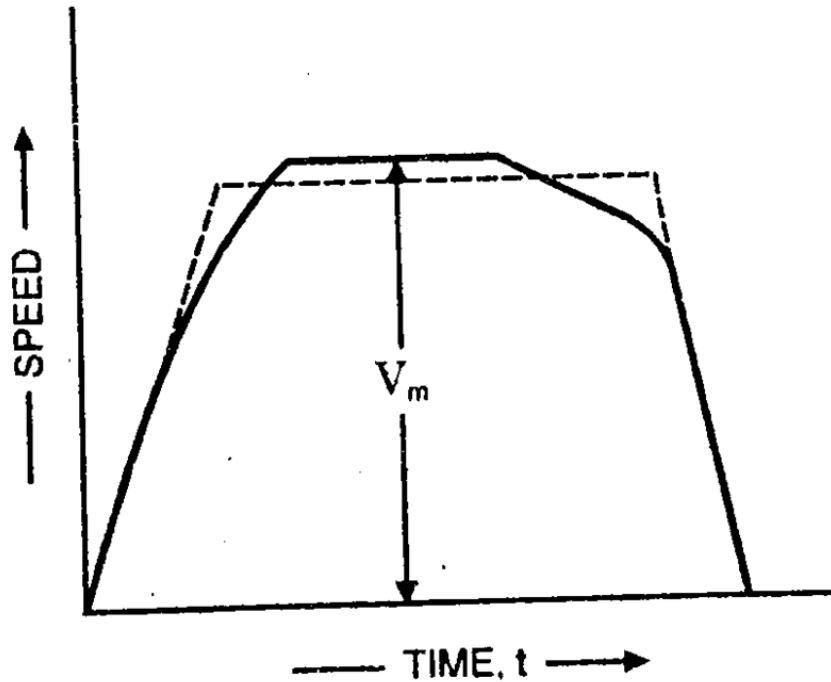
The mean of the speeds from start to stop, the distance covered between two stops divided by the actual time of run is known as Average Speed.

$$\text{Schedule Speed} = \frac{\text{Distance between stops}}{\text{Actual time of run} + \text{Stop time}}$$

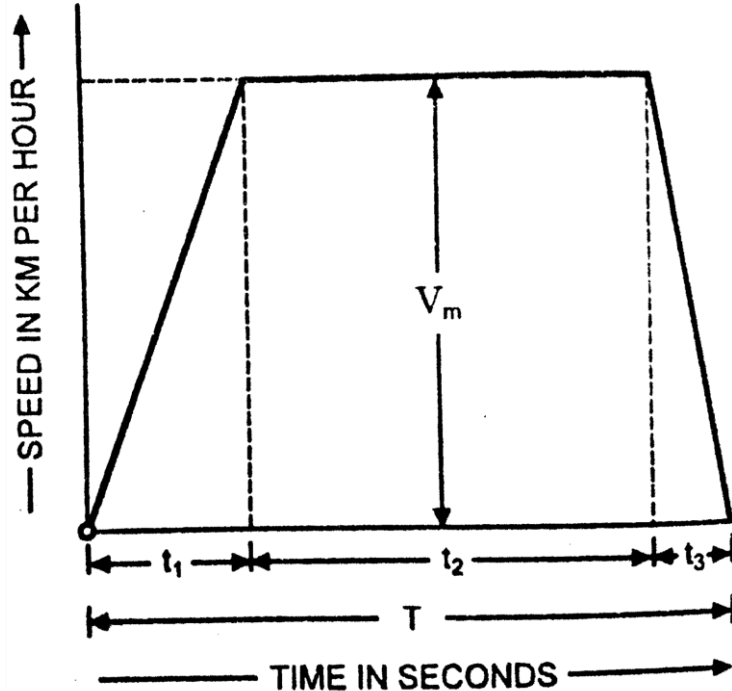
◦ Schedule Speed:

The ratio of distance covered between two stops divided by the actual time of run including time of stop is known as Schedule Speed.

Simplified Speed - Time Curve



Trapezoidal Speed - Time Curve



Let α = Acceleration in kmphs
 β = Retardation in kmphs
 V_m = Crest speed in kmph
 T = Total time of run in seconds.

Time for acceleration in seconds, $t_1 = \frac{V_m}{\alpha}$

Time for retardation in seconds, $t_3 = \frac{V_m}{\beta}$

Trapezoidal Speed – Time Curve

Time for free running in seconds, $t_2 = T - (t_1 + t_3) = T - \left(\frac{V_m}{\alpha} + \frac{V_m}{\beta} \right)$

Total distance of run in km, $S =$ Distance travelled during acceleration + distance travelled during free run + distance travelled during braking

$$= \frac{1}{2} V_m \frac{t_1}{3,600} + V_m \frac{t_2}{3,600} + \frac{1}{2} V_m \frac{t_3}{3,600}$$

Substituting $t_1 = \frac{V_m}{\alpha}$, $t_3 = \frac{V_m}{\beta}$ and $t_2 = T - \left(\frac{V_m}{\alpha} + \frac{V_m}{\beta} \right)$ we get

$$S = \frac{V_m^2}{7,200\alpha} + \frac{V_m}{3,600} \left[T - \left(\frac{V_m}{\alpha} + \frac{V_m}{\beta} \right) \right] + \frac{V_m^2}{7,200\beta}$$

$$\text{or } S = \frac{V_m^2}{7,200\alpha} + \frac{V_m}{3,600} T - \frac{V_m^2}{3,600\alpha} - \frac{V_m^2}{3,600\beta} + \frac{V_m^2}{7,200\beta}$$

$$= \frac{V_m T}{3,600} - \frac{V_m^2}{7,200\alpha} - \frac{V_m^2}{7,200\beta} \quad \dots(11.1)$$

Trapezoidal Speed – Time Curve

$$\text{or } \frac{V_m^2}{3,600} \left(\frac{1}{2\alpha} + \frac{1}{2\beta} \right) - \frac{V_m T}{3,600} + S = 0$$

$$\text{or } V_m^2 \left(\frac{1}{2\alpha} + \frac{1}{2\beta} \right) - V_m T + 3,600S = 0$$

This is a quadratic equation for V_m . Substituting $\frac{1}{2\alpha} + \frac{1}{2\beta} = K$, we get

$$KV_m^2 - V_m T + 3,600S = 0$$

$$\text{or } V_m = \frac{T \pm \sqrt{T^2 - 4K \times 3,600S}}{2K} = \frac{T}{2K} \pm \sqrt{\frac{T^2}{4K^2} - \frac{3,600S}{K}}$$

The + ve sign cannot be adopted, as value of V_m obtained by using + ve sign will be much higher than that is possible in practice. Hence – ve sign will be used and, therefore, we have

$$V_m = \frac{T}{2K} - \sqrt{\frac{T^2}{4K^2} - \frac{3,600S}{K}} \quad \dots(11.2)$$

From the above equation unknown quantity can be determined by substituting the value of known quantities.

Different Traction System

Non Electric

- **Direct Steam Engine Drive**
- **Direct IC Engine Drive**

Electric

- **Steam Electric Drive**
- **IC Engine Electric Drive**
- **Petrol Electric Traction**
- **Battery Electric Drive**
- **Electric Drive**

Classification of Locomotives

**Self
Contained
Locomotive**

- **Diesel**
- **Steam**
- **Battery**
- **Diesel Electric**

**Locomotive
obtaining
energy
from
external
source**

- **DC**
- **AC**
- **Dual (AC&DC)**

System of Track Electrification

DC System

- 600V – 750V Suburban (SS : 3 – 5 km)
- 1500V – 3000V Main Line Service (SS : 15 – 40 km)

Single Phase AC System

- 15kV – 25kV, 25Hz (SS : 50 – 80 km)

Three Phase AC System

- 3000V – 3600V, 25Hz

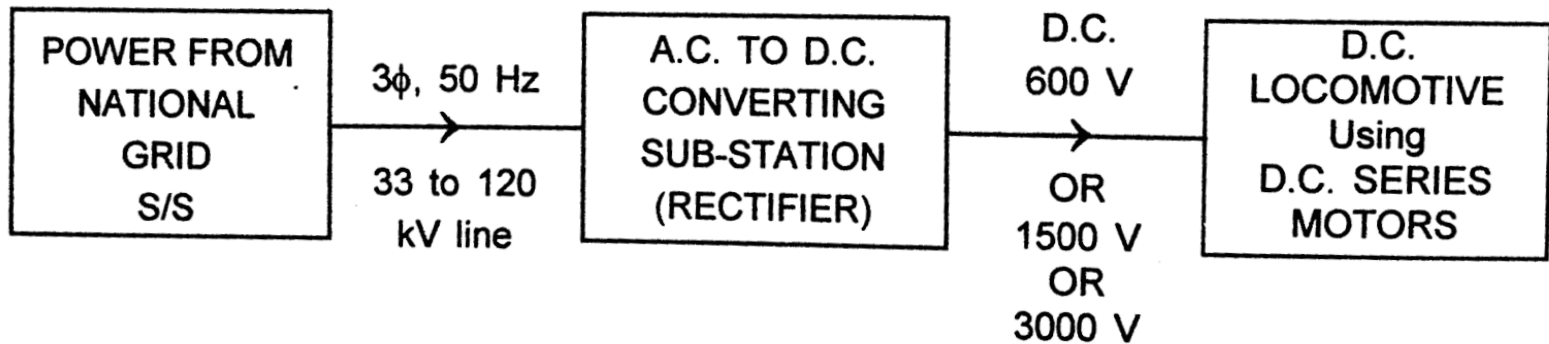
Composite System

- KANDO (1 Φ - 3 Φ) System
- 1 Φ - DC System

System of Track Electrification

DC System

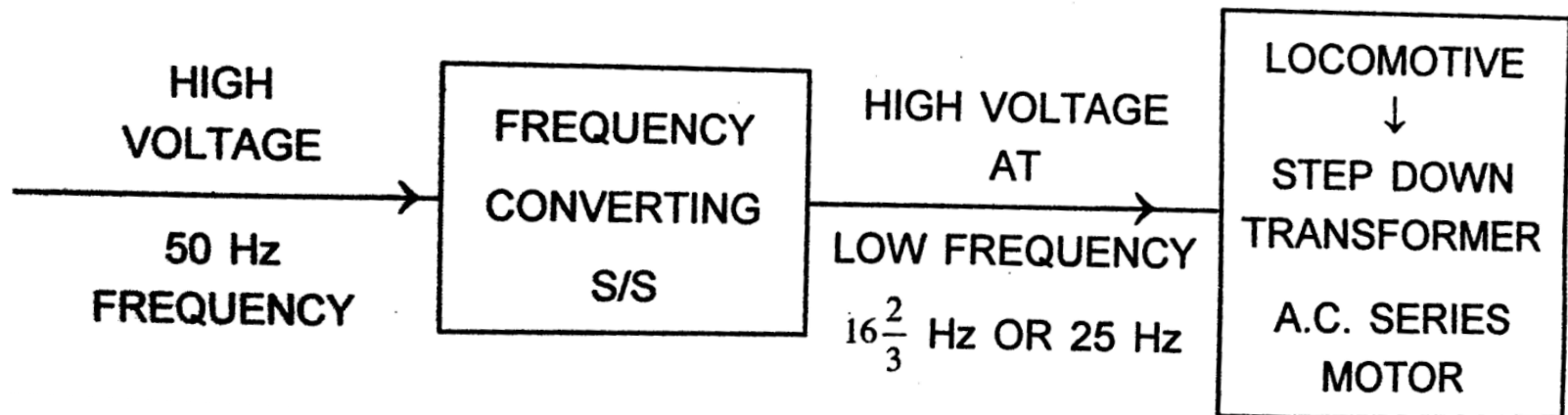
- 600V – 750V Suburban (SS : 3 – 5 km)
- 1500V – 3000V Main Line Service (SS : 15 – 40 km)



System of Track Electrification

Single Phase Low Frequency AC System

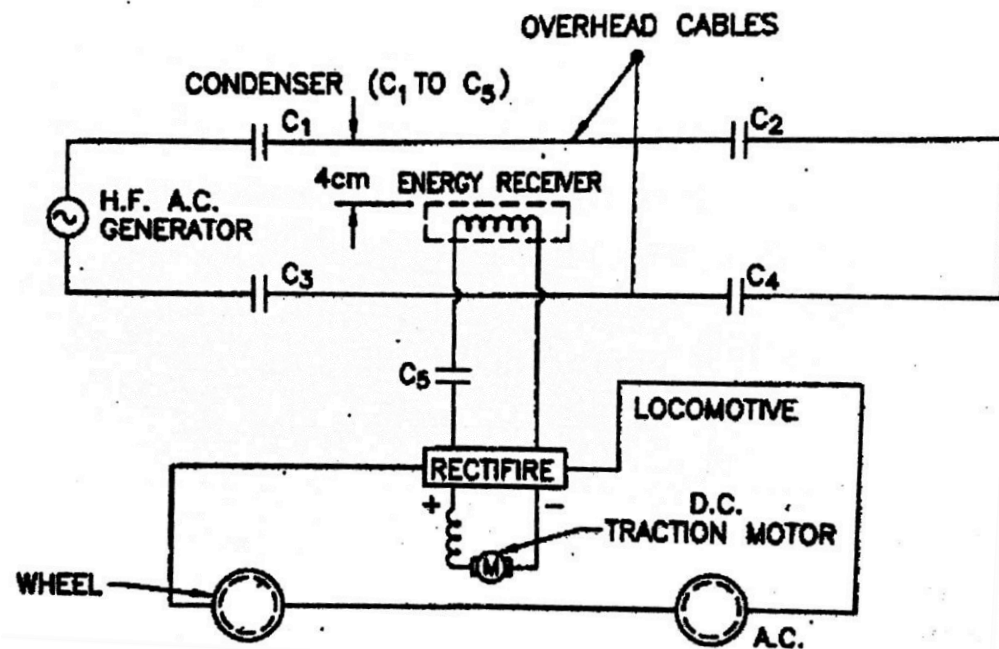
- 15kV – 25kV, 25Hz (SS : 50 – 80 km)



System of Track Electrification

Single Phase High Frequency AC System

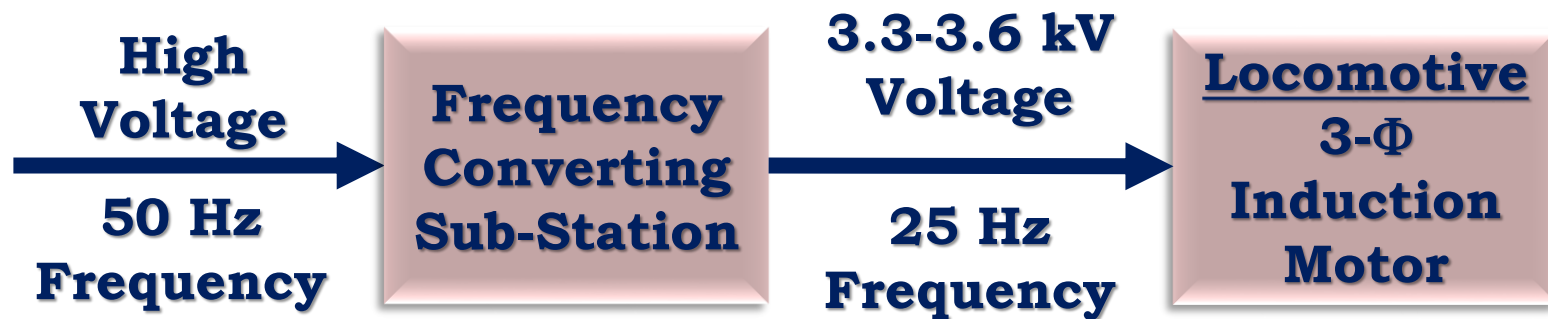
- Several Volt, 2.5kHz – 3kHz (Coal Mines)



System of Track Electrification

Three Phase AC System

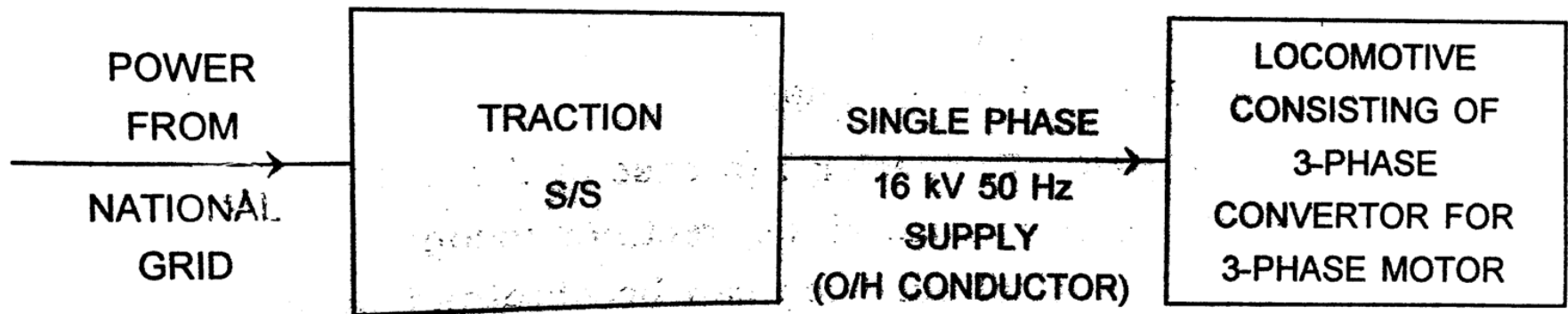
- 3000V – 3600V, 25Hz



System of Track Electrification

Composite System

- KANDO ($1\Phi - 3\Phi$) System
- $1\Phi - DC$ System



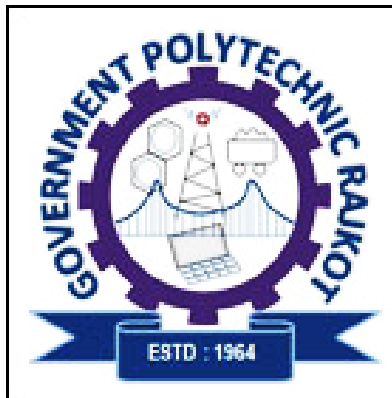
Reference

Utilization of Electrical Power &

Electric Traction – J B Gupta

Publication : S K Kataria & Sons

Thank You



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